

Satisfiability of ATL with strategy contexts

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LIAFA LSV



Paris, 18-21 September 2013

Outline of the presentation

- 1 Temporal logics for games: ATL and extensions
 - expressing properties of complex interacting systems
 - extensions to non-zero-sum games
- 2 From ATL with strategy contexts to QCTL
 - QCTL is CTL with propositional quantification
 - strategies encoded as propositions on the computation tree
- 3 Satisfiability of ATL with strategy contexts
 - QCTL satisfiability is decidable, but...
 - ATL_{SC} satisfiability is not, except for turn-based games

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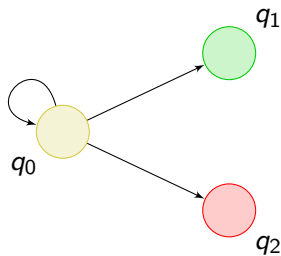
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Reasoning about multi-agent systems

Concurrent games

A **concurrent game** is made of

- a transition system;
- a set of **agents** (or **players**);
- a table indicating the transition to be taken given the actions of the players.



		player 1		
				
player 2				
				
				

Reasoning about multi-agent systems

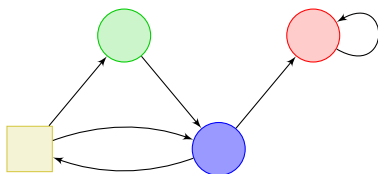
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Turn-based games

A **turn-based game** is a game where only one agent plays at a time.



Reasoning about open systems




Strategies

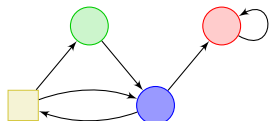
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Strategy for player :
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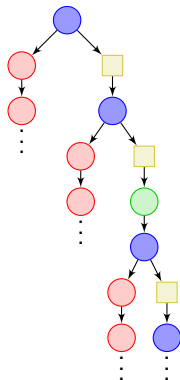
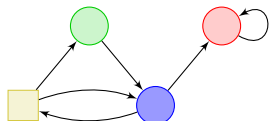


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Temporal logics for games: ATL [AHK02]

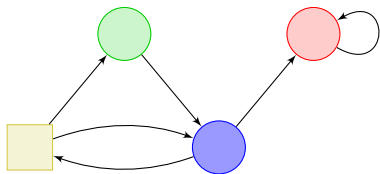
ATL extends CTL with **strategy quantifiers**

$\langle\langle A \rangle\rangle \varphi$ expresses that A has a strategy to enforce φ .

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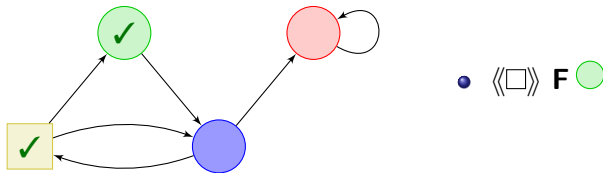


• $\langle\langle \square \rangle\rangle \mathbf{F} \text{ Green Circle}$

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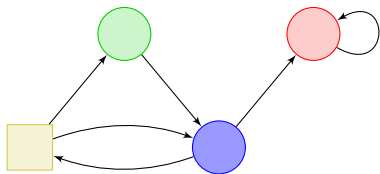
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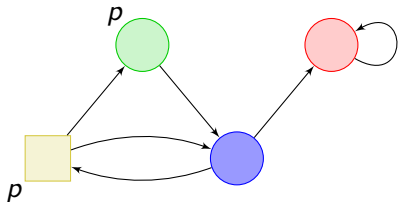


- $\langle\langle \square \rangle\rangle \mathbf{F} \text{ } \bullet$
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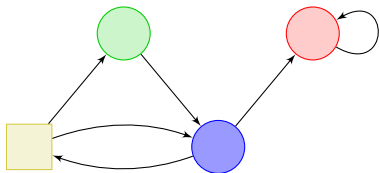
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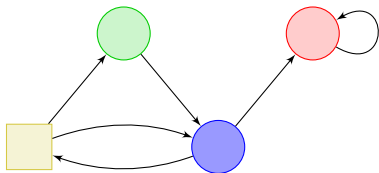
- $\langle\langle \circ \rangle\rangle \mathbf{G}(\underbrace{\langle\langle \square \rangle\rangle \mathbf{F} \text{ (green circle)}}_p) \equiv \langle\langle \circ \rangle\rangle \mathbf{G} p$

Another semantics: ATL with strategy contexts [BDLM09]

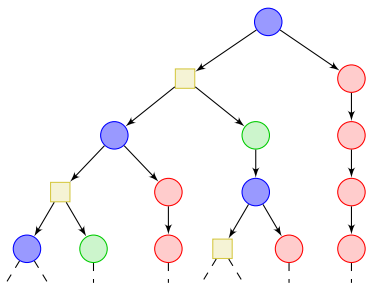


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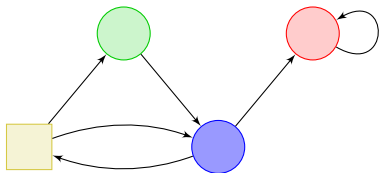


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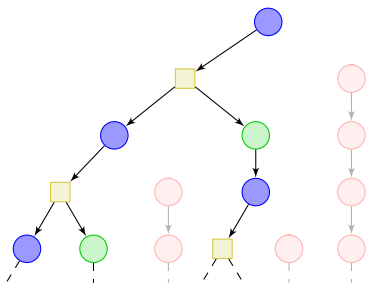


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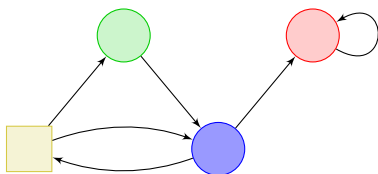


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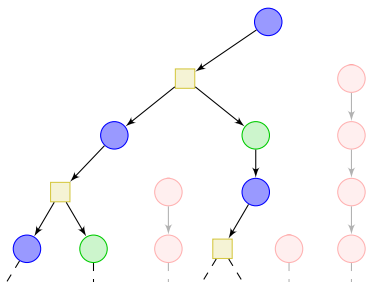


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- consider the following strategy of Player $\color{blue}\bullet$: “always go to \square ”;
- in the remaining tree, Player $\color{yellow}\square$ can always enforce a visit to $\color{green}\circ$.

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- Client-server interactions for accessing a shared resource:

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- Existence of Nash equilibria:

$$\langle A_1, \dots, A_n \rangle \bigwedge_i (\langle A_i \cdot \rangle \varphi_{A_i} \Rightarrow \varphi_{A_i})$$

- Existence of dominating strategy:

$$\langle A \cdot \rangle [B] (\neg \varphi \Rightarrow [A] \neg \varphi)$$

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Quantified CTL [Kup95,Fre01]

QCTL extends CTL with **propositional quantifiers**

$\exists p. \varphi$ means that **there exists a labelling** of the model with p under which φ holds.

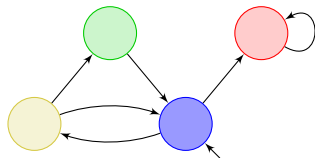
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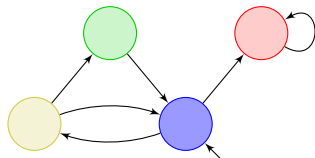
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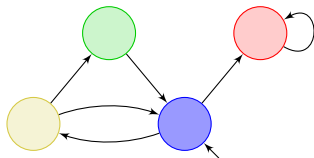


- $\mathbf{EF} \textcircled{red} \wedge \forall p. [\mathbf{EF}(p \wedge \textcircled{red}) \Rightarrow \mathbf{AG}(\textcircled{red} \Rightarrow p)] \equiv \text{uniq}(\textcircled{red})$

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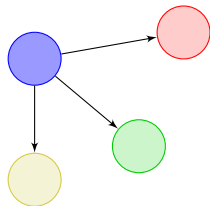


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↪ true if we label the Kripke structure;

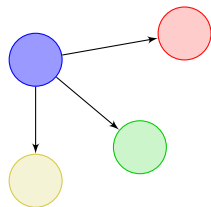
↪ false if we label the computation tree;

Translating ATL_{sc} into QCTL



- player A has moves m_1^A, \dots, m_n^A ;
- from the transition table, we can compute the set $\text{Next}(\text{blue circle}, A, m_i^A)$ of states that can be reached from blue circle when player A plays m_i^A .

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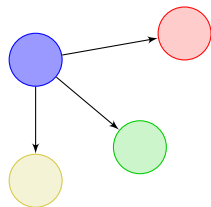
$\langle A \rangle \varphi$ can be encoded as follows:

$\exists m_1^A. \exists m_2^A \dots \exists m_n^A.$

- this corresponds to a strategy: $\mathbf{A} \mathbf{G}(m_i^A \Leftrightarrow \bigwedge \neg m_j^A)$;
- the outcomes all satisfy φ :

$\mathbf{A} [\mathbf{G}(q \wedge m_i^A \Rightarrow \mathbf{X} \text{Next}(q, A, m_i^A)) \Rightarrow \varphi].$

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Theorem (DLM12)

QCTL model checking is decidable (in the tree semantics).

Corollary

ATL_{sc} model checking is decidable.

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Why?

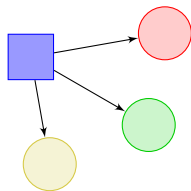


The translation from ATL_{SC} to QCTL assumes that the game structure is fixed!

Satisfiability for turn-based games

Theorem (LM13b)

When restricted to turn-based games, ATL_{sc} satisfiability is decidable.



- player \square has moves \circ , \circ and \circ .
- a strategy can be encoded by marking some of the nodes of the tree with proposition mov_A .

$\langle A \rangle \varphi$ can be encoded as follows:

$\exists \text{mov}_A.$

- it corresponds to a strategy: $\mathbf{A} \mathbf{G}(\text{turn}_A \Rightarrow \mathbf{E} \mathbf{X}_1 \text{mov}_A)$;
- the outcomes all satisfy φ : $\mathbf{A} [\mathbf{G}(\text{turn}_A \wedge \mathbf{X} \text{mov}_A) \Rightarrow \varphi]$.

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One move in each state of the structure (**not** of its execution tree).

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Theorem

Model checking ATL_{sc} with only memoryless quantification is PSPACE-complete.

However:

Theorem

Satisfiability of ATL_{sc} with memoryless quantification is undecidable (even on turn-based structures).

What about Strategy Logic [CHP07,MMV10]?

Strategy logic

Explicit quantification over strategies + strategy assignement

Strategy logic can also be translated into QCTL.

Theorem

- *Strategy-logic satisfiability is decidable when restricted to turn-based games.*
- *Memoryless strategy-logic satisfiability is undecidable.*

Conclusions and future works

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- ATL_{sc} is a very powerful logic for reasoning about games.
- QCTL is a nice tool to understand such logics.
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Future directions

- Defining interesting (expressive yet tractable) fragments of those logics;
- Obtaining practicable algorithms.
- Considering randomised strategies.