
Advanced numerical computation of χ^2 tests for fault detection and isolation

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Gaussian residual evaluation — χ^2 -tests

Consider m -dimensional residual $\mathbf{z} \sim \mathcal{N}(M\boldsymbol{\eta}, \Sigma)$
with $M \in \mathbb{R}^{m \times n}$, $\boldsymbol{\eta} \in \mathbb{R}^n$, $\Sigma \in \mathbb{R}^{m \times m}$, $m \geq n$.

Fault detection

$H_0 : \boldsymbol{\eta} = \mathbf{0}$ against $H_1 : \boldsymbol{\eta} \neq \mathbf{0}$

Fault isolation for some partition $\boldsymbol{\eta} = \begin{bmatrix} \boldsymbol{\eta}_a \\ \boldsymbol{\eta}_b \end{bmatrix}$

$H_0 : \boldsymbol{\eta}_a = \mathbf{0}$ against $H_1 : \boldsymbol{\eta}_a \neq \mathbf{0}$

These hypothesis testing problems lead to χ^2 -tests.

Introduction

- Typical fault detection and isolation (FDI) procedure:
 - residual generation
 - residual evaluation
- Evaluation of Gaussian residuals
 - for parametric change in linear systems
 - for small parametric change in nonlinear systems
(local asymptotic approach to change detection)
- Changes in the mean of a Gaussian vector — χ^2 -tests

Basic formulas for the χ^2 -tests

$$\mathbf{z} \sim \mathcal{N}(M\boldsymbol{\eta}, \Sigma) \quad \mathbf{I} = M^T \Sigma^{-1} M \quad \boldsymbol{\eta} = \begin{bmatrix} \boldsymbol{\eta}_a \\ \boldsymbol{\eta}_b \end{bmatrix} \quad M = [M_a \ M_b] \quad \mathbf{I} = \begin{bmatrix} \mathbf{I}_{aa} & \mathbf{I}_{ab} \\ \mathbf{I}_{ba} & \mathbf{I}_{bb} \end{bmatrix}$$

Fault detection (global test)

$$t = \mathbf{z}^T \Sigma^{-1} M (M^T \Sigma^{-1} M_a)^{-1} M_a^T \Sigma^{-1} \mathbf{z}$$

Fault isolation by sensitivity test

$$\tilde{t}_a = \mathbf{z}^T \Sigma^{-1} M_a (M_a^T \Sigma^{-1} M_a)^{-1} M_a^T \Sigma^{-1} \mathbf{z}$$

or equivalently

$$\begin{aligned} \tilde{\boldsymbol{\zeta}}_a &= M_a^T \Sigma^{-1} \mathbf{z} \\ \tilde{t}_a &= \tilde{\boldsymbol{\zeta}}_a^T \mathbf{I}_{aa}^{-1} \tilde{\boldsymbol{\zeta}}_a \end{aligned}$$

Basic formulas of the χ^2 -tests (contd.)

Fault isolation by **min-max test**

$$\begin{aligned}\tilde{\zeta}_a &= M_a^T \Sigma^{-1} z \\ \tilde{\zeta}_b &= M_b^T \Sigma^{-1} z \\ \zeta_a^* &= \tilde{\zeta}_a - \mathbf{I}_{ab} \mathbf{I}_{bb}^{-1} \tilde{\zeta}_b \\ \mathbf{I}_a^* &= \mathbf{I}_{aa} - \mathbf{I}_{ab} \mathbf{I}_{bb}^{-1} \mathbf{I}_{ba} \\ t_a^* &= \zeta_a^{*T} \mathbf{I}_a^{*-1} \zeta_a^*\end{aligned}$$

Numerical difficulties: when the matrices to be inverted are badly conditioned, these basic formulas can lead to large numerical errors. It is thus important to develop advanced numerical algorithms.

Advanced numerical computation – Sensitivity test

$$\tilde{t}_a = z^T \Sigma^{-1} M_a (M_a^T \Sigma^{-1} M_a)^{-1} M_a^T \Sigma^{-1} z$$

Same as global test (M being replaced by M_a).

Advanced numerical computation:

QR decomposition of ΓM_a : $\Gamma M_a = Q_a R_a$ with $Q_a^T Q_a = I$, then

$$\tilde{t}_a = \|Q_a^T \Gamma z\|^2$$

Advanced numerical computation – Global test

$$t = z^T \Sigma^{-1} M (M^T \Sigma^{-1} M)^{-1} M^T \Sigma^{-1} z$$

- Use pseudo-inverse for Σ^{-1} if badly conditioned
- Compute t as a square : $t = \|(M^T \Sigma^{-1} M)^{-\frac{1}{2}} M^T \Sigma^{-1} z\|^2$
- Avoid the inverse involving M .

Proposed solution:

- let $\Gamma = \Sigma^{-\frac{1}{2}}$ (with pseudo-inverse if necessary),
- QR decomposition of ΓM : $\Gamma M = QR$ with $Q^T Q = I$,
- Then

$$\begin{aligned}t &= z^T \Gamma Q R (R^T Q^T Q R)^{-1} R^T Q^T \Gamma z \\ &= z^T \Gamma Q R (R^T R)^{-1} R^T Q^T \Gamma z \\ &= \|Q^T \Gamma z\|^2\end{aligned}$$

Advanced numerical computation – Minmax test

More computations are involved.

QR decompositions:

$$\begin{aligned}\Gamma M_a &= Q_a R_a \\ \Gamma M_b &= Q_b R_b \\ (I - Q_b Q_b^T) Q_a &= Q_c R_c\end{aligned}$$

then

$$t_a^* = \|Q_c^T \Gamma z\|^2$$

A non-trivial step for deriving the algorithm:

$$(I - Q_a^T Q_b Q_b^T Q_a) = Q_a^T (I - Q_b Q_b^T) (I - Q_b Q_b^T) Q_a$$

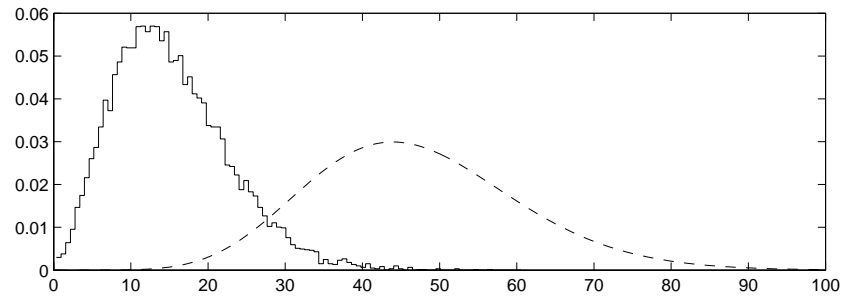
Remark: SVD can be used instead of QR decomposition.

A numerical example

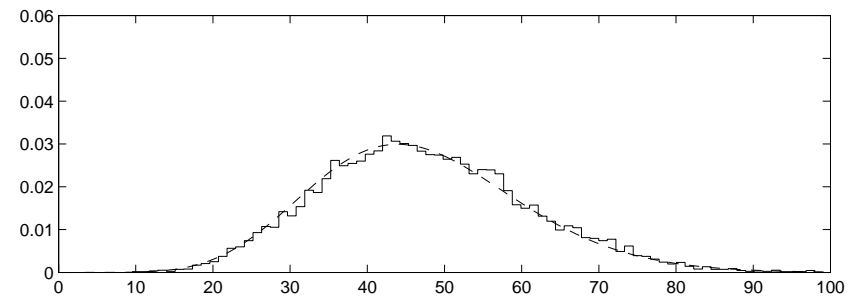
Gaussian vector: $\dim(z) = 9, \dim(\eta) = 5, \dim(\eta_a) = 2$.

Condition number of Σ : 3.4×10^{10} .

Histograms are based on 10000 random realizations.



Basic minmax test (solid line) and $\chi^2(2, 44.955)$ density function (dashed line).



Advanced minmax test (solid line) and $\chi^2(2, 44.955)$ density function (dashed line).

Conclusion

- χ^2 -tests are frequently used for residual evaluation.
- Advanced numerical algorithms can significantly improve the numerical accuracy of badly conditioned problems.