Importance Splitting for Statistical Model Checking Rare Properties

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- What has been done before
 - Monte Carlo approach
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 - A solution: Importance Sampling
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- Numerical model checking
 - precise
 - exhaustive exploration of state space
 - limited model size
- Statistical model checking
 - statistical model of executions
 - results within confidence bounds
 - trades off tractability with precision





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Properties

Properties specified with time bounded temporal logic:

•
$$\phi = \alpha \mid \phi \lor \phi \mid \phi \land \phi \mid \neg \phi \mid \mathbf{X}\phi \mid \mathbf{F}^{\mathsf{t}}\phi \mid \mathbf{G}^{\mathsf{t}}\phi \mid \phi \mathbf{U}^{\mathsf{t}}\phi$$

- X is the next operator,
- Ft is the bounded eventually operator,
- Gt, is the bounded globally operator
- Ut is the bounded until operator.



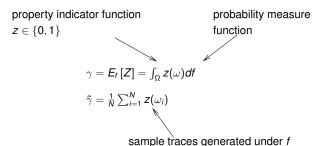
Objective

- Standard Statistical technique for SMC: Monte Carlo.
- Rare events often cause serious failures but are difficult to simulate.
- Given a stochastic system, design a procedure for estimating a rare property in a reasonable time with SMC.



Monte Carlo Model Checking

- Goal: Given a Markovian system and a property φ , compute the probability γ that a path ω satisfies φ , i.e. $(\gamma = P[\omega \models \varphi])$.
- The behavior of the system with respect to the property can be modeled by a Bernoulli random variable Z.



Monte Carlo estimation



$$A = \{\omega \in \Omega : z(\omega) = 1\} \quad (1)$$

$$\tilde{\gamma} = \frac{1}{N} \sum_{i=1}^{n} z(\omega_i)$$
 (2)

Absolute error = half the size of the confidence interval

$$AE \propto \frac{\sqrt{\gamma(1-\gamma)}}{\sqrt{N}}$$
 (3)





Main Problems with Rare Events

- ullet Occur with small probability (e.g. $< 10^{-6}$)
 - appear rarely in stochastic simulations
 - need very large number of trials to see single example
 - without seeing, cannot quantify how low the probability
- The absolute error is not useful: $(\gamma \pm \epsilon)$ is "large" if $\epsilon \gg \gamma$
 - \bullet Bounds (e.g. Chernoff) not useful when γ small
 - Unbounded relative error:

$$RE = \frac{\sqrt{Var(Z)}}{\sqrt{N}E[Z]} = \frac{\sqrt{\gamma(1-\gamma)}}{\sqrt{N}\gamma} \underset{\gamma \to 0}{\approx} = \frac{1}{\sqrt{N\gamma}}$$
(4)





Importance Sampling

Monte Carlo

•
$$\gamma = \int_{\Omega} z(\omega) df$$

$$\tilde{\gamma}_{MC} = \frac{1}{N} \sum_{i=1}^{n} z(\omega_i)$$

Traces generated under f

Importance Sampling

•
$$\gamma = \int_{\Omega} z(\omega) \frac{f(\omega)}{f'(\omega)} df'$$

•
$$\tilde{\gamma}_{IS} = \frac{1}{N} \sum_{i=1}^{n} z(\omega_i) \frac{f(\omega_i)}{f'(\omega_i)}$$

• Traces generated under f'





Tilted simulation



0

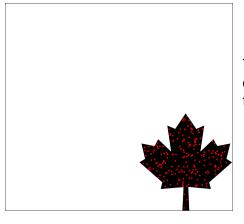
$$\tilde{\gamma}_{IS} = \frac{1}{N} \sum_{i=1}^{n} z(\omega_i) \frac{f(\omega_i)}{f'(\omega_i)}$$

 Traces generated under f' (Importance Sampling distribution)





Optimal Importance Sampling



There exists an optimal distribution: *f* conditioned on the rare event:

$$f^{opt} = \frac{zf}{\gamma}$$
 (5)





Monte Carlo approach
Rare Events
A solution: Importance Sampling

Limitations of Importance Sampling

- Quantifying the performance of apparently "good" distributions is an open problem.
- Problem of accuracy with long simulations: variance of the estimators increases.
- Implies the need of an alternative technique: Importance Splitting.



Basics of Importance Splitting

Let *A* be a rare event and $(A_k)_{0 \le k \le n}$ be a sequence of nested events:

$$A_0\supset A_1\supset...\supset A_n=A \tag{6}$$

By Bayes formula,

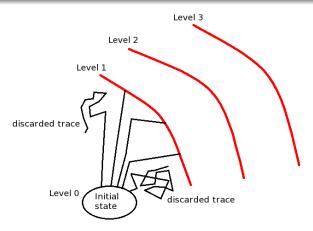
$$\gamma \stackrel{\text{def}}{=} P(A) = P(A_0)P(A_1 \mid A_0)P(A_2 \mid A_1)...P(A_n \mid A_{n-1})$$
 (7)

implying that every conditionnal probability is less rare:

$$\forall k, P(A_k \mid A_{k-1}) = \gamma_k \ge \gamma \tag{8}$$

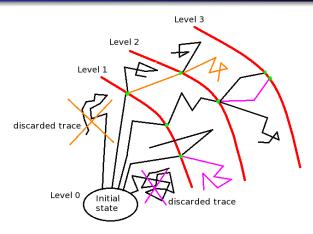


Example: Reaching Level 3 in finite time





Example: Reaching Level 3 in finite time



P(reaching Level 3)=3/5*2/5*2/5



Importance Splitting in a Model Checking Context

Idea: given a rare property φ , define a set of levels based on a sequence of temporal properties such that:

$$(\varphi_k)_{0 \le k \le n} : \varphi_0 \Leftarrow \varphi_1 \Leftarrow \dots \Leftarrow \varphi_n = \varphi \tag{9}$$

Thus,

$$\gamma = P(\omega \models \varphi_0) \prod_{k=1}^n P(\omega \models \varphi_k \mid \omega \models \varphi_{k-1})$$
 (10)





Simple Decomposition

- When $\varphi = \bigwedge_{j=1}^n \psi_j$, a decomposition into nested properties is: $\varphi_i = \bigwedge_{i=1}^j \psi_i$, $\forall i \in \{1, ..., n\}$ with $\varphi_0 = \top$
- Possibility to choose an arbitrary order of sub-formulae:
- Ex: Given $\varphi = a \wedge b \wedge c$,
 - $\varphi_3 = a \wedge b \wedge c$, $\varphi_2 = a \wedge b$, $\varphi_1 = c$
 - $\varphi_3 = a \wedge b \wedge c$, $\varphi_2 = b \wedge c$, $\varphi_1 = a$
 - Both decompositions are valid.

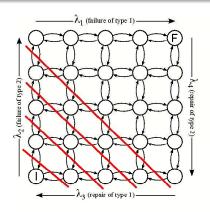


Natural Decomposition

- Many rare events are defined with a natural notion of level, when some quantity of the system reaches a particular value.
- In Computational systems: might refer to a loop counter, a number of software objects, etc...
- In physical systems: might refer to a temperature, a distance, a number of molecules...
- Natural levels defined by nested atomic properties: $\varphi_i = (x > x_i)$ with x a state variable and $\omega \models \varphi_n \Leftrightarrow x \ge x_n$.



Decomposition of Temporal Operators



- Repair model
- $\varphi = \text{init} \wedge \mathbf{X} \left(\neg \text{init } \mathbf{U^t} \text{ fail} \right) \text{ with }$ init $\Leftrightarrow (x = 0)$ and fail $\Leftrightarrow (x = n)$.
- Decomposition:

$$\forall k \in \{1,...,n\}, \ \varphi_k =$$
init $\land \mathbf{X} (\neg \text{init } \mathbf{U}^{\mathbf{t}} (x \geq k))$





Fluctuation Analysis

• $(1 - \alpha)$ Confidence Interval based on the relative variance

$$\sigma \colon \left[\tilde{\gamma} \left(\frac{1}{1 + \frac{z_{\alpha} \sigma}{\sqrt{N}}} \right) ; \tilde{\gamma} \left(\frac{1}{1 - \frac{z_{\alpha} \sigma}{\sqrt{N}}} \right) \right] \text{ with } \sigma^2 \ge \sum_{k=1}^m \frac{1 - \gamma_k}{\gamma_k}$$

- Inequality arises because the independence of initial states diminishes with increasing levels.
- Several possibilities minimise this dependence effect.





Idealized Version

- Relative variance of the estimator: $\sigma^2 = \sum_{k=1}^m \frac{1-\gamma_k}{\gamma_k}$
- For a fixed number of levels, this variance is minimal if all the conditional probabilities are equal (∃ρ ∈]0; 1[s.t.∀k, γ_k = ρ)
- Problem: levels might be too coarse.





Score functions

- Score function goal: increase the resolution of levels.
- Level-based score functions: Mapping from logical properties to

 R which give information on the number of satisfied sub-formulae.

$$S(\omega) = \max_{k} \left\{ k \mid \omega \models \varphi_{k} \right\} \tag{11}$$

• General score functions: Mapping from sets of paths to $\mathbb R$ s.t. higher scores assigned to paths that satisfy the overall property.

$$S(\omega) = \max_{\omega \le j} P\left(\varphi \mid \omega \le j\right) \tag{12}$$





Use of heuristics

- Level-based score functions correlate logic to score.
- General score functions requires:
 - higher scores assigned to paths that satisfy the overall property.
 - $P(\phi \mid \omega') \ge P(\phi \mid \omega) \Rightarrow S(\omega') \ge S(\omega)$
- In some case, the shortest paths satisfying a rare property are the most likely => possibility to exploit the length of a path to improve a score function based on coarse logical levels.



Dining Philosophers Problem

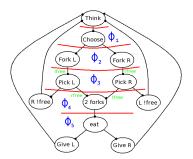


Figure: Automata modelling a philosopher

- 150 philosophers
- more than 2¹⁴⁴ states
- property of interest: $\varphi = \mathbf{F}^{30}$ (Phil i eat)





Experimental Results given by an adaptive algorithm

- based on A. Guyader, F. Cérou, T. Furon, Del Moral work (2007)
- predefined $\gamma_k \approx 0.85$,
- The algorithm finds adaptively around 96 iterations,
- gain of time: between 800 and 5000 times faster than Monte Carlo





Experimental Results given by an adaptive algorithm

	Importance Splitting					MC
number of experiments	100	100	100	100	1	1
nb of paths	50	100	200	500	1000	10 million
time (seconds)	0,66	1,73	4,08	11,64	24,17	>5 hours
estimate (average)	1,42	1,52	1,59	1,58	1,53	1,2
standard deviation	1,63	1,02	0,87	0,5	-	0,35
Relative Error (average)	0,72	0,45	0,31	0,19	0,13	0,29
95%-CI lower bound	0,82	1,04	1,22	1,33	1,35	0,52
95%-CI upper bound	5,08	2,76	2,29	1,95	1,76	1,88

Results are times 10^6 *6% wrong



Summary

- Rare events are often critical.
- Importance splitting is a rare event technique that admits a confidence bound and is applicable to many systems.
- We have defined how importance splitting may be combined with temporal logic to apply SMC to rare events.
- Score functions generalise the notion of levels required by importance splitting
- Heuristics may be used to increase the granularity of score functions to improve performance.



Ongoing work

- Improved confidence bounds
- Integration in Statistical Model Checker PLASMA
- Case studies: false alarm of derailment, collision of particles?



