

Coq a dit : fromage tranché ne peut cacher ses trous

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Static backward slicing (introduced by Weiser in 1981)

- simplifies a given program p w.r.t. a point of interest C (**slicing criterion**, typically a statement)
- removes irrelevant statements that do not impact C
- is based on control and data dependencies
- produces a simplified program q (**slice**)

Definitions

- **WHILE language**: skip, $x := e$, if, while, with usual expressions and fixed-size arrays, error-free

Control dependence

```
if (l: b) {  
  ...  
  li: stmti;  
  ...  
} else {  
  ...  
  lj: stmtj;  
  ...  
}
```

```
while (l: b) {  
  ...  
  li: stmti;  
  ...  
}
```

Data dependence

```
l: x = e; //def  
... // x not assigned  
... // x not assigned  
... // x not assigned  
l1: y = ... x ...; //use
```

- **Dependence-based slice** q of p w.r.t. C : all statements on which one of the statements of C is (directly or indirectly) dependent
- Formally: $q = \{l \in p \mid l \rightarrow^* l', l' \in C\}$,
where $\rightarrow = \xrightarrow{ctrl} \cup \xrightarrow{data}$

Classic soundness property

Theorem (Classic soundness property)

Let σ be an input state of p . Suppose that p halts on σ . Then q halts on σ and the executions of p and q on σ agree after each statement preserved in the slice on the variables that appear in this statement.

- Formalized with a trajectory-based semantics
- Equality of projection for the trajectories of p and q
- Does this result hold in the general case, i.e. in presence of errors and non-termination ? And more precisely:
 - If an error is found in q , is it also present in p ?
 - If there are no errors in q , what can be said about p ?

Assertions

- WHILE language: skip, $x:=e$, if, while, **assert**
- Assertions make runtime errors explicit
- Assertions protect all statements that may cause a runtime error


```
assert (l: N != 0);
```

```
l1: x = k/N;
```


```
assert (l: k < N);
```

```
l1: x = a[k];
```

Case 1: same error




```
1 s1 = 0;
2 s2 = 0;
3 i = 0;
4 while (i < N){
5     assert (i < N);
6     s1 = s1 + a[i];
7     i = i + k;
8 }
9 j = 0;
10 assert (k != 0);
11 last = N/k;
12 while (j <= last){
13     assert (k*j < N);
14     s2 = s2 + a[k*j];
15     j = j + 1;
16 }
17 assert (N != 0);
18 avg1 = s1 / N;
19 assert (N != 0);
20 avg2 = s2 / N;
21 if (avg1 == avg2)
22     print("equal");
```




```
1 s1 = 0;
2 s2 = 0;
3 i = 0;
4 while (i < N){
5     assert (i < N);
6     s1 = s1 + a[i];
7     i = i + k;
8 }
9 j = 0;
10 assert (k != 0);
11 last = N/k;
12 while (j <= last){
13     assert (k*j < N);
14     s2 = s2 + a[k*j];
15     j = j + 1;
16 }
17 assert (N != 0);
18 avg1 = s1 / N;
19 assert (N != 0);
20 avg2 = s2 / N;
21 if (avg1 == avg2)
22     print("equal");
```

Example execution for test input: $N = 2$, $k = 4$

Case 2: error hidden by another error (not preserved)



```
1 s1 = 0;
2 s2 = 0;
3 i = 0;
4 while (i < N){
5     assert (i < N);
6     s1 = s1 + a[i];
7     i = i + k;
8 }
9 j = 0;
10 assert (k != 0);
11 last = N/k;
12 while (j <= last){
13     assert (k*j < N);
14     s2 = s2 + a[k*j];
15     j = j + 1;
16 }
17 assert (N != 0);
18 avg1 = s1 / N;
19 assert (N != 0);
20 avg2 = s2 / N;
21 if (avg1 == avg2)
22     print("equal");
```



```
1 s1 = 0;
2 s2 = 0;
3 i = 0;
4 while (i < N){
5     assert (i < N);
6     s1 = s1 + a[i];
7     i = i + k;
8 }
9 j = 0;
10 assert (k != 0);
11 last = N/k;
12 while (j <= last){
13     assert (k*j < N);
14     s2 = s2 + a[k*j];
15     j = j + 1;
16 }
17 assert (N != 0);
18 avg1 = s1 / N;
19 assert (N != 0);
20 avg2 = s2 / N;
21 if (avg1 == avg2)
22     print("equal");
```

Example execution for test input: $N = 0, k = 0$

Case 3: error hidden by a loop (not preserved)



```
1 s1 = 0;
2 s2 = 0;
3 i = 0;
4 while (i < N){
5     assert (i < N);
6     s1 = s1 + a[i];
7     i = i + k;
8 }
9 j = 0;
10 assert (k != 0);
11 last = N/k;
12 while (j <= last){
13     assert (k*j < N);
14     s2 = s2 + a[k*j];
15     j = j + 1;
16 }
17 assert (N != 0);
18 avg1 = s1 / N;
19 assert (N != 0);
20 avg2 = s2 / N;
21 if (avg1 == avg2)
22     print("equal");
```



```
1 s1 = 0;
2 s2 = 0;
3 i = 0;
4 while (i < N){
5     assert (i < N);
6     s1 = s1 + a[i];
7     i = i + k;
8 }
9 j = 0;
10 assert (k != 0);
11 last = N/k;
12 while (j <= last){
13     assert (k*j < N);
14     s2 = s2 + a[k*j];
15     j = j + 1;
16 }
17 assert (N != 0);
18 avg1 = s1 / N;
19 assert (N != 0);
20 avg2 = s2 / N;
21 if (avg1 == avg2)
22     print("equal");
```


Example execution for test input: $N = 4, k = 0$


- Classic property does not hold in the general case
- Two solutions:
 - adding more dependencies
 - 😊 Keep classic soundness property
 - 😞 Bigger slices
 - keep same dependencies
 - 😊 Keep slices small
 - ⚠️ Another soundness property required

- Classic property does not hold in the general case
- Two solutions:
 - adding more dependencies
 - 😊 Keep classic soundness property
 - 😞 Bigger slices
 - **keep same dependencies**
 - 😊 Keep slices small
 - ⚠️ Another soundness property required

- In addition to (unmodified) control and data dependencies, assert dependence between an assertion and its protected statement

Assertion dependence

 `assert (1: N != 0);`
`l1: x = k/N;`

 `assert (1: k < N);`
`l1: x = a[k];`

- **Relaxed slice** q of p w.r.t. C : all statements on which one of the statements of C is (directly or indirectly) dependent
- Formally: $q = \{l \in p \mid l \rightarrow^* l', l' \in C\}$,
where $\rightarrow = \xrightarrow{ctrl} \cup \xrightarrow{data} \cup \xrightarrow{assert}$

Soundness property of relaxed slicing


Theorem

The projection of the trajectory of p is a prefix of the projection of the trajectory of q . If the execution of p terminates normally, the projections are equal.


In the absence of errors and non-termination, the classic property holds.



Case 2: error hidden by another error (not preserved)



```
1 s1 = 0;
2 s2 = 0;
3 i = 0;
4 while (i < N){
5     assert (i < N);
6     s1 = s1 + a[i];
7     i = i + k;
8 }
9 j = 0;
10 assert (k != 0);
11 last = N/k;
12 while (j <= last){
13     assert (k*j < N);
14     s2 = s2 + a[k*j];
15     j = j + 1;
16 }
17 assert (N != 0);
18 avg1 = s1 / N;
19 assert (N != 0);
20 avg2 = s2 / N;
21 if (avg1 == avg2)
22     print("equal");
```



```
1 s1 = 0;
2 s2 = 0;
3 i = 0;
4 while (i < N){
5     assert (i < N);
6     s1 = s1 + a[i];
7     i = i + k;
8 }
9 j = 0;
10 assert (k != 0);
11 last = N/k;
12 while (j <= last){
13     assert (k*j < N);
14     s2 = s2 + a[k*j];
15     j = j + 1;
16 }
17 assert (N != 0);
18 avg1 = s1 / N;
19 assert (N != 0);
20 avg2 = s2 / N;
21 if (avg1 == avg2)
22     print("equal");
```

Example execution for test input: $N = 0, k = 0$

Verification on relaxed slices

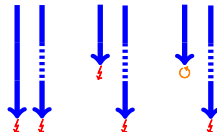
Theorem (No errors in the slice)

If there are no runtime errors in q , then there are none in p , in the statements preserved in q .

```
✓1 s1 = 0;
? 2 s2 = 0;
✓3 i = 0;
✓4 while (i < N){
✓5   assert (i < N);
✓6   s1 = s1 + a[i];
✓7   i = i + k;
✓8 }
? 9 j = 0;
?10 assert (k != 0);
?11 last = N/k;
?12 while (j <= last){
?13   assert (k*j < N);
?14   s2 = s2 + a[k*j];
?15   j = j + 1;
?16 }
✓17 assert (N != 0);
✓18 avg1 = s1 / N;
?19 assert (N != 0);
?20 avg2 = s2 / N;
?21 if (avg1 == avg2)
?22   print("equal");
```

Theorem (An error in the slice)

If there is a runtime error in q , then either the same error occurs in p , or another error or an infinite loop caused by a statement not preserved in q masks it.



Earlier definition of data
dependence

```
1: x = e; //def  
... // x not assigned  
... // x not assigned  
... // x not assigned  
l1: y = ... x ...; //use
```

Not easy to use in induction proofs
 $data(p1; p2) = ?$

We introduce:

- $maydef(p) = \{(l, x) \mid l \text{ can be the last definition of } x \text{ in } p\}$
- $mayuse(p) = \{(l, x) \mid x \text{ can be read at } l \text{ before being defined}\}$
- $mustdef(p) = \{x \mid x \text{ is always defined by } p\}$
- $mayuse(p_1; p_2) = mayuse(p_1) \cup (mayuse(p_2) \setminus mustdef(p_1))$
- $data(p_1; p_2) = data(p_1) \cup data(p_2) \cup$
 $\{(l, l') \in (p_1, p_2) \mid \exists x : (l, x) \in maydef(p_1) \wedge$
 $(l', x) \in mayuse(p_2)\}$

Conclusion:

- Relaxed slicing: soundness, yet slices of reasonable size
- A formal link about the presence or the absence of errors in the program and its slices
- Formalization in Coq (10,000 LOC)
- Certified slicer in Ocaml extracted from Coq

Future work:

- Consider a wider class of errors
- Extend the language
- Measure the benefits of relaxed slicing for verification

References:

Léchenet, J-C., Kosmatov, N., Le Gall, P. : Cut Branches Before Looking for Bugs: Sound Verification on Relaxed Slices. In FASE (2016). To appear.

Demo: extracted slicer on an example

Slice of the program in test_prog w.r.t. line 9.

```
$ ./test_slice.byte test_prog \[9\]
```

```
Original program:
0: ASSERT (not ((x1) <= (0))) && (not ((x1) == (0))) =>> 0;
1: ASSERT (not ((x5) <= (0))) && (not ((x5) == (0))) =>> 1;
WHILE 2: not ((x5) == (0)) DO
  3: x10 := 0;
  4: x11 := x1;
  WHILE 5: (x11) <= (x5) DO
    6: x10 := (x10) + (1);
    7: x11 := (x11) + (x1)
  END;
  8: x1 := x5;
  9: x5 := x11
END
```

```
Slice:
WHILE 2: not ((x5) == (0)) DO
  4: x11 := x1;
  WHILE 5: (x11) <= (x5) DO
    7: x11 := (x11) + (x1)
  END;
  8: x1 := x5;
  9: x5 := x11
END
```

