

How to implement the belief functions

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- ▶ Natural order
- ▶ Smets codes
- ▶ General framework
- ▶ How to obtain bbas?
 - ▶ Random bbas
 - ▶ Distance based model
 - ▶ probabilistic based model

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Discernment frame: $\Theta = \{\theta_1, \theta_2, \dots, \theta_n\}$

Power set: all the disjunctions of Θ :

$$2^\Theta = \{\emptyset, \{\theta_1\}, \{\theta_2\}, \{\theta_1 \cup \theta_2\}, \dots, \Theta\}$$

Natural order:

$$2^\Theta = \{\emptyset, \{\theta_1\}, \{\theta_2\}, \{\theta_1 \cup \theta_2\}, \\ \{\theta_3\}, \{\theta_1 \cup \theta_3\}, \{\theta_2 \cup \theta_3\}, \{\theta_1 \cup \theta_2 \cup \theta_3\}, \\ \{\theta_4\}, \dots, \Theta\}$$

Natural order:

\emptyset 0	θ_1 1	θ_2 2	$\theta_1 \cup \theta_2$ $3 = 2^2 - 1$
θ_3 $4 = 2^{3-1} + 1$	$\theta_1 \cup \theta_3$ 5	$\theta_2 \cup \theta_3$ 6	$\theta_1 \cup \theta_2 \cup \theta_3$ $7 = 2^3 - 1$
θ_4 $8 = 2^{4-1} + 1$
θ_i $2^{i-1} + 1$	Θ 2^n

Bba in Matlab:

Example: $m_1(\theta_1) = 0.5$, $m_1(\theta_3) = 0.4$, $m_1(\theta_1 \cup \theta_2 \cup \theta_3) = 0.1$
 $m_2(\theta_3) = 0.4$, $m_2(\theta_1 \cup \theta_3) = 0.4$

F1=[1 4 7]';

F2=[4 5]';

M1=[0.5 0.4 0.1]';

M2=[0.4 0.6]';

Combination

$$m_{\text{Conj}}(X) = \sum_{Y_1 \cap Y_2 = X} m_1(Y_1) m_2(Y_2) \quad (1)$$

$\theta_1 \cap (\theta_1 \cup \theta_3): 1 \cap 5$

In binary on base 3: $1=100$ and $5=101=100 \mid 001$

$100 \& 101 = 100$

In Matlab:

```
sizeDS=3;
F1=[1 4 7]';
F2=[4 5]';
M1=[0.5 0.4 0.1]';
M2=[0.4 0.6]';
Fres=[];
Mres=[];
for i=1:size(F1)
    for j=1:size(F2)
        Fres=[Fres bi2de(de2bi(F1(i),sizeDS)&de2bi(F2(j),sizeDS)))]';
        Mres=[Mres M1(i)*M2(j)];
    end
end
```


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Smets gives the codes of the Mobius transform (see Only_Mobius_Transf) for conversions:

- ▶ bba and belief: mtobel, beltom
- ▶ bba and plausibility: mtopl, pltom
- ▶ bba and communality: mtoq, qtom
- ▶ bba and implicability: mtob, btom
- ▶ bba to pignistic probability: mtobetp
- ▶ etc...

e.g. in Matlab:

```
m1=[0 0.4 0.1 0.2 0.2 0 0 0.1]';
```

```
mtobel(m1)
```

```
gives: 0 0.4000 0.1000 0.7000 0.2000 0.6000 0.3000 1.0000
```

Conjunctive combination

$$m_{\text{Conj}}(X) = \sum_{Y_1 \cap \dots \cap Y_m = X} \prod_{j=1}^m m_j(Y_j)$$

The practical way:

$$q(X) = \prod_{j=1}^m q_j(X)$$

Disjunctive combination

$$m_{\text{Dis}}(X) = \sum_{Y_1 \cup \dots \cup Y_m = X} \prod_{j=1}^m m_j(Y_j)$$

The practical way:

$$b(X) = \prod_{j=1}^m b_j(X)$$

In Matlab

For the conjunctive rule of combination:

```
m1=[0 0.4 0.1 0.2 0.2 0 0 0.1]';
```

```
m2=[0 0.2 0.3 0.1 0.1 0 0.2 0.1]';
```

```
q1=mtoq(m1);
```

```
q2=mtoq(m2);
```

```
qConj=q1.*q2;
```

```
mConj=qtom(qConj)
```

```
mConj =
```

```
0.4100 0.2200 0.2000 0.0500 0.0900 0 0.0200 0.0100
```

In Matlab

For the disjunctive rule of combination:

```
m1=[0 0.4 0.1 0.2 0.2 0 0 0.1]';
```

```
m2=[0 0.2 0.3 0.1 0.1 0 0.2 0.1]';
```

```
b1=mtob(m1);
```

```
b2=mtob(m2);
```

```
bConj=b1.*b2;
```

```
bDis=b1.*b2;
```

```
mDis=btom(bDis)
```

```
mDis =
```

```
0 0.0800 0.0300 0.3100 0.0200 0.0800 0.1300 0.3500
```

Once bbas are combined, to decide just use the functions mtobel, mtopl or mtobetp, etc.

In Matlab

```
mtopl(mConj)
```

```
0 0.2800 0.2800 0.5000 0.1200 0.3900 0.3700 0.5900
```

```
mtobetp(mConj)
```

```
0.4209 0.4040 0.1751
```

```
mtopl(mDis)
```

```
0 0.8200 0.8200 0.9800 0.5800 0.9700 0.9200 1.0000
```

```
mtobetp(mDis)
```

```
0.3917 0.3667 0.2417
```

DST code for the combination:

- ▶ criteria=1 Smets criteria
- ▶ criteria=2 Dempster-Shafer criteria (normalized)
- ▶ criteria=3 Yager criteria
- ▶ criteria=4 disjunctive combination criteria
- ▶ criteria=5 Dubois criteria (normalized and disjunctive combination)
- ▶ criteria=6 Dubois and Prade criteria (mixt combination)
- ▶ criteria=7 Florea criteria
- ▶ criteria=8 PCR6
- ▶ criteria=9 Cautious Denoeux Min for non-dogmatics functions
- ▶ criteria=10 Cautious Denoeux Max for separable functions
- ▶ criteria=11 Hard Denoeux for fonctions sous-normales
- ▶ criteria=12 Mean of the bbas

Transfers the partial conflict on focal elements given this conflict proportionnaly to the masses.

$$m_{\text{PCR5}}(X) = m_{\text{Conj}}(X) + \sum_{\substack{Y \in 2^\Theta, \\ X \cap Y = \emptyset}} \left(\frac{m_1(X)^2 m_2(Y)}{m_1(X) + m_2(Y)} + \frac{m_2(X)^2 m_1(Y)}{m_2(X) + m_1(Y)} \right)$$

$$m_{\text{PCR6}}(X) = m_{\text{Conj}}(X) + \sum_{j=1}^s m_j(X)^2 \sum_{\substack{\bigcap_{j'=1}^{s-1} Y_{\sigma_j(j')} \cap X = \emptyset \\ (Y_{\sigma_j(1)}, \dots, Y_{\sigma_j(s-1)}) \in (2^\Theta)^{s-1}}} \left(\frac{\prod_{j'=1}^{s-1} m_{\sigma_j(j')}(Y_{\sigma_j(j')})}{m_j(X) + \sum_{j'=1}^{s-1} m_{\sigma_j(j')}(Y_{\sigma_j(j')})} \right)$$

decisionDST code for the decision:

- ▶ criteria=1 maximum of the plausibility
- ▶ criteria=2 maximum of the credibility
- ▶ criteria=3 maximum of the credibility with rejection
- ▶ criteria=4 maximum of the pignistic probability
- ▶ criteria=5 Appriou criteria

test.m:

```
m1=[0 0.4 0.1 0.2 0.2 0 0 0.1]';
```

```
m2=[0 0.2 0.3 0.1 0.1 0 0.2 0.1]';
```

```
m3=[0.1 0.2 0 0.4 0.1 0.1 0 0.1]';
```

```
m3d=discounting(m3,0.95);
```

```
M_comb_Smets=DST([m1 m2 m3d],1);
```

```
M_comb_PCR6=DST([m1 m2],8);
```

```
class_fusion=decisionDST(M_comb_Smets',1)
```

```
class_fusion=decisionDST(M_comb_PCR6',1)
```

```
class_fusion=decisionDST(M_comb_Smets',5,0.5)
```

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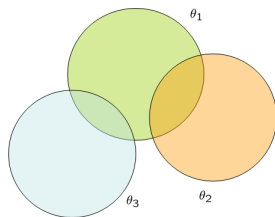
- ▶ Main problem of the DST code: all element must be coded (not only the focal elements)
- ▶ Only usable for belief functions defined on power set (2^Θ)
- ▶ General belief functions framework works for power set and hyper power set (D^Θ)

DSmT introduced by Dezert, 2002.

- ▶ D^Θ closed set by union and intersection operators
- ▶ D^Θ is not closed by complementary, $A \in D^\Theta \not\Rightarrow \bar{A} \in D^\Theta$
- ▶ if $|\Theta| = n$: $2^\Theta \ll D^\Theta \ll 2^{2^\Theta}$
- ▶ D_r^Θ : reduced set considering some constraints ($\theta_2 \cap \theta_3 \equiv \emptyset$)

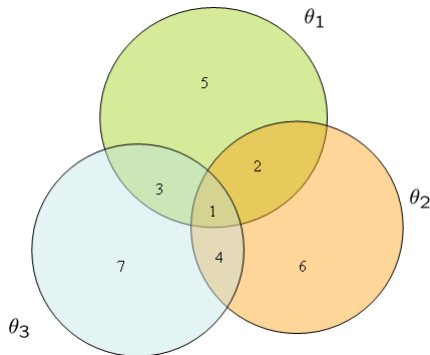
$$\text{GPT}(X) = \sum_{Y \in D_r^\Theta, Y \neq \emptyset} \frac{\mathcal{C}_M(X \cap Y)}{\mathcal{C}_M(Y)} m(Y)$$

where $\mathcal{C}_M(X)$ is the cardinality of X in D_r^Θ



A simple codification (Martin, 2009)

Affect an integer of $[1; 2^n - 1]$ to each distinct part of Venn diagram de Venn ($n = |\Theta|$)



$$\Theta = \{[1\ 2\ 3\ 5], [1\ 2\ 4\ 6], [1\ 3\ 4\ 7]\}$$

Adding a constraint: if $\Theta = \{[1\ 2\ 3\ 5], [1\ 2\ 4\ 6], [1\ 3\ 4\ 7]\}$ and we know $\theta_2 \cap \theta_3 \equiv \emptyset$ (i.e. $\theta_2 \cap \theta_3 \notin D_r^\Theta$)

The parts 1 and 4 of Venn diagram does not exist:

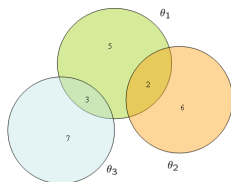
$$\Theta_r = \{[2\ 3\ 5], [2\ 6], [3\ 7]\}$$

Operations on focal elements

$$\theta_1 \cap \theta_3 = [3]$$

$$\theta_1 \cup \theta_3 = [2\ 3\ 5\ 7]$$

$$(\theta_1 \cap \theta_3) \cup \theta_2 = [2\ 3\ 6]$$



The cardinality $\mathcal{C}_M(X)$: the number of intergers in the codification of X

Gives an easy Matlab programming of the combination rules and the decision functions

Decoding: to present the decision or a result to the human - *The codification is not understandable*

If the decision set is given, we just have to sweep the corresponding part of D_r^Θ

Without any knowledge of the element to decode:

1. We can use the Smarandache condification more lisible but less practical in Matlab
2. We sweep all D_r^Θ (first considering 2^Θ). There is a combinatorial risk.



Description of the problem

CardTheta=3; % cardinality of Theta

% list of experts with focal elements and associated bba

```
expert(1).focal='1' '1u3' '3' '1u2u3';
```

```
expert(1).bba=[0.5 0.3 0.1 0.1];
```

```
expert(2).focal='1' '2' '1u3' '1u2u3';
```

```
expert(2).bba=[0.5 0.6 0.1 0.1];
```

```
expert(3).focal='1' '3n2' '(1n2)u3';
```

```
expert(3).bba=[0.2 0.7 0.1];
```

constraint=""; % set of empty elements e.g. '1n2'

In test.m

Description of the problem

elemDec='A'; % set of decision elements:

- ▶ list of elements on which we can decide,
- ▶ A for all,
- ▶ S for singletons only,
- ▶ F for focal elements only,
- ▶ SF for singleton plus focal elements,
- ▶ Cm for given specificity, e.g. elemDec='Cm' '1' '4'; minimum of cardinality 1, maximum=4,
- ▶ 2T for only 2^Θ (DST case)

Parameters

Combination criterium

criteriumComb = is the combination criterium

- ▶ criteriumComb=1 Smets criterium
- ▶ criteriumComb=2 Dempster-Shafer criterium (normalized)
- ▶ criteriumComb=3 Yager criterium
- ▶ criteriumComb=4 disjunctive combination criterium
- ▶ criteriumComb=5 Florea criterium
- ▶ criteriumComb=6 PCR6
- ▶ criteriumComb=7 Mean of the bbas

Parameters

Combination criterium

criteriumComb = is the combination criterium

- ▶ criteriumComb=8 Dubois criterium (normalized and disjunctive combination)
- ▶ criteriumComb=9 Dubois and Prade criterium (mixt combination)
- ▶ criteriumComb=10 Mixt Combination (Martin and Osswald criterium)
- ▶ criteriumComb=11 DPCR (Martin and Osswald criterium)
- ▶ criteriumComb=12 MDPCR (Martin and Osswald criterium)
- ▶ criteriumComb=13 Zhang's rule

Parameters

Decision criterium

criteriumDec = is the combination criterium

- ▶ criteriumDec=0 maximum of the bba
- ▶ criteriumDec=1 maximum of the pignistic probability
- ▶ criteriumDec=2 maximum of the credibility
- ▶ criteriumDec=3 maximum of the credibility with reject
- ▶ criteriumDec=4 maximum of the plausibility
- ▶ criteriumDec=5 Appriou criterium
- ▶ criteriumDec=6 DS_mP criterium

Parameters

Mode of fusion

mode='static'; % or 'dynamic'

Display

display = kind of display

- ▶ display = 0 for no display,
- ▶ display = 1 for combination display,
- ▶ display = 2 for decision display,
- ▶ display = 3 for both displays

Fusion

fuse(expert,constraint,CardTheta,criteriumComb,criteriumDec,mode,elemDec,display)

Called functions:

- ▶ Coding: call coding, addConstraint, codingExpert
- ▶ Combination: call combination
- ▶ Decision: call decision
- ▶ Display: call decodingExpert, decodingFocal

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In Matlab:

1. ThetaSize=3;
2. nbFocalElement=4;
3. ind=randperm(2^ThetaSize);
4. indFocalElement=ind(1:nbFocalElement);
5. randMass=diff([0; sort(rand(nbFocalElement-1,1)); 1]);
We take the difference between 3 ordered random number in [0,1], e.g. diff([0; [0.3; 0.9] ; 1]) gives 0.3 0.6 0.1
6. MasseOut(indFocalElement,i)=randMass;

- ▶ focal elements can be evrywhere:
`ind=randperm(2^ThetaSize);`
- ▶ focal elements not on the emptyset:
`ind =1+randperm(2^ThetaSize-1);`
- ▶ no dogmatic mass: one focal element is on Theta (ignorance):
`ind =[2^ThetaSize randperm(2^ThetaSize-1)];`
- ▶ no dogmatic mass: one focal element is on Theta (ignorance)
and focal elements are not on the emptyset
`ind =[2^ThetaSize (1+randperm(2^ThetaSize-2))]`
(nbFocalElement==ThetaSize):
- ▶ all the focal elements are the singletons:
`ind=[];`
for `i=1:ThetaSize`
 `ind=[ind; 1+2^(i-1)];`
end

Only θ_i and Θ are focal elements, $n * m$ sources (experts)

- ▶ Prototypes case (\mathbf{x}_i center of θ_i). For the observation x

$$m_j^i(\theta_i) = \alpha_{ij} \exp[-\gamma_{ij} d^2(x, \mathbf{x}_i)]$$

$$m_j^i(\Theta) = 1 - \alpha_{ij} \exp[-\gamma_{ij} d^2(x, \mathbf{x}_i)]$$

- ▶ $0 \leq \alpha_{ij} \leq 1$: discounting coefficient and $\gamma_{ij} > 0$, are parameters to play on the quantity of ignorance and on the form of the mass functions
- ▶ The distance allows to give a mass to x higher according to the proximity to θ_i
- ▶ belief k -nn: we consider the k -nearest neighbors instead to \mathbf{x}_i
- ▶ Then we combine the bbas

In Matlab (Denoëux codes)

See ExampleIris.m

```
load iris
```

```
ind=randperm(150);
```

```
xapp=x(ind(1:100),:);
```

```
Sapp=S(ind(1:100));
```

```
xtst=x(ind(101:150),:);
```

```
Stst=S(ind(101:150));
```

```
[gamm,alpha] = knndsinit(xapp,Sapp); % initialization
```

```
[gamm,alpha,err] = knndsfit(xapp,Sapp,5,gamm,0); % parameter  
optimization
```

```
[m,L] =knndsval(xapp,Sapp,5,gamm,alpha,0,xtst); % test
```

```
[value,Sfind]=max(m);
```

```
[mat_conf,vect_prob_classif,vect_prob_error]=build_conf_matrix(Sfind,Stst)
```

- ▶ Need to estimate $p(S_j|\theta_i)$
- ▶ 2 models proposed by Appriou according to both axioms:
 1. the $n * m$ couples $[M_i^j, \alpha_{ij}]$ are distinct information sources where focal elements are: θ_i, θ_i^c and Θ
 2. If $M_i^j = 0$ and the information is valid ($\alpha_{ij} = 1$) then it is certain that θ_i is not true.

$$\begin{array}{ll} \text{Model 1: } m_j^i(\theta_i) = M_i^j & \text{Model 2: } m_j^i(\Theta) = M_i^j \\ m_j^i(\theta_i^c) = 1 - M_i^j & m_j^i(\theta_i^c) = 1 - M_i^j \end{array}$$

Adding the reliability α_{ij} with the discounting:

Model 1:

$$\begin{array}{ll} m_j^i(\theta_i) & = \alpha_{ij} M_i^j \\ m_j^i(\theta_i^c) & = \alpha_{ij} (1 - M_i^j) \\ m_j^i(\Theta) & = 1 - \alpha_{ij} \end{array}$$

Model 2:

$$\begin{array}{ll} m_j^i(\theta_i) & = 0 \\ m_j^i(\theta_i^c) & = \alpha_{ij} (1 - M_i^j) \\ m_j^i(\Theta) & = 1 - \alpha_{ij} (1 - M_i^j) \end{array}$$

How to find M_i^j ?

3th axiom:

- 3 Conformity to the Bayesian approach (case where $p(S_j|\theta_j)$ is exactly the reality ($\alpha_{ij} = 1$) for all i, j) and all the *a priori* probabilities $p(\theta_i)$ are known)

$$\text{Model 1: } M_i^j = \frac{R_j p(S_j | \theta_j)}{1 + R_j p(S_j | \theta_j)}$$

$$m_j^i(\theta_i) = \frac{\alpha_{ij} R_j p(S_j | \theta_j)}{1 + R_j p(S_j | \theta_j)}$$

$$m_j^i(\theta_i^c) = \frac{\alpha_{ij}}{1 + R_j p(S_j | \theta_j)}$$

$$m_j^i(\Theta) = 1 - \alpha_{ij}$$

with $R_j \geq 0$ a normalization factor.

Model 2: $M_i^j = R_j p(S_j | \theta_j)$

$$m_j^i(\theta_i) = 0$$

$$m_j^i(\theta_i^c) = \alpha_{ij}(1 - R_j p(S_j | \theta_j))$$

$$m_j^i(\Theta) = 1 - \alpha_{ij}(1 - R_j p(S_j | \theta_j))$$

with $R_j \in [0, (\max_{S_j, i}(p(S_j | \theta_j)))^{-1}]$

In practical:

- ▶ α_{ij} : discounting coefficient fixed near 1 and $p(S_j | \theta_j)$ can be given by the confusion matrix
- ▶ Adapted to the cases where we learn one class against all the others

In Matlab:

- ▶ take the previous confusion matrix or `mat_conf=[68 12 22 ; 9 42 5 ; 8 2 87]`
- ▶ `mat_masse= bbaType(mat_conf,alpha,model)`: gives all the possible bbas (*i.e.* number of classes) for the given confusion matrix, alpha (a constant such as 0.95) and the model (1 or 2)
- ▶ `bbas=buildBbas(Stst,mat_conf,alpha,model)`: gives the bbas resulting of the founded classes given in Stst

Difficulties:

- ▶ Appriou: learning the probabilities $p(S_j|\theta_j)$
- ▶ Denœux: choice of the distance $d(x, \mathbf{x}_i)$

Easiness:

- ▶ $p(S_j|\theta_j)$ easier to estimate on decisions with the confusion matrix of the classifiers
- ▶ $d(x, \mathbf{x}_i)$ easier to choose on the numeric outputs of classifiers (ex.: Euclidian distance)

- ▶ **Toolboxes:**
<http://www.bfasociety.org/wiki/index.php/Toolboxes>
- ▶ **a lot of papers on:**
<http://www.bfasociety.org/wiki/extensions/Wikindx/wikindx3/index.php>

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Honorary Members

A.P. Dempster **G. Shafer**

The theory of belief functions, also referred to as evidence theory or Dempster-Shafer theory, was first introduced by Arthur P. Dempster in the context of statistical inference, and was later developed by Glenn Shafer as a general framework for modeling epistemic uncertainty.

Forthcoming

The **BFAS** is a society dedicated to the development and use of belief functions within any area of society. Both commercial and academics alike are welcomed to contribute to the society.

Belief functions allow for the modelling of subjectivity in a non bayesian manner using probabilistic mathematics.

Contributions take place via newsletters, educational school camps, and the bi-annual conference. The recent 2010 conference in Brest, France was hugely successful inaugural event, with attendance by many of the most noted Belief Function advocates from around the globe.

- ▶ On the presented codes:
 - ▶ Kennes R. and Smets Ph. (1991) Computational Aspects of the Möbius Transformation. Uncertainty in Artificial Intelligence 6, P.P. Bonissone, M. Henrion, L.N. Kanal, J.F. Lemmer (Editors), Elsevier Science Publishers (1991) 401-416.
 - ▶ A. Martin, Implementing general belief function framework with a practical codification for low complexity, in Advances and Applications of DSMT for Information Fusion, American Research Press Rehoboth, pp. 217-273, 2009.
 - ▶ T. Denœux. A k-nearest neighbor classification rule based on Dempster-Shafer theory. IEEE Transactions on Systems, Man and Cybernetics, 25(05):804-813, 1995.
 - ▶ L. M. Zouhal and T. Denœux. An evidence-theoretic k-NN rule with parameter optimization. IEEE Transactions on Systems, Man and Cybernetics - Part C, 28(2):263-271,1998.
 - ▶ Appriou, Discrimination multisignal par la théorie de l'évidence, chap 7, Décision et Reconnaissance des formes en signal, Hermes Science Publication, 2002, 219-258

- ▶ Other way to code belief functions:
 - ▶ P.P. Shenoy and G. Shafer. Propagating belief functions with local computations. IEEE Expert, 1(3):43-51, 1986.
 - ▶ R. Haenni and N. Lehmann. Implementing belief function computations. International Journal of Intelligent Systems, Special issue on the Dempster-Shafer theory of evidence, 18(1):31-49, 2003.
 - ▶ C. Liu, D. Grenier, A.-L. Josselme, É. Bossé, Reducing algorithm complexity for computing an aggregate uncertainty measure, IEEE Transactions on Systems, Man and Cybernetics-Part A: Systems and Humans 37: 669-679, 2007.
 - ▶ V.-N. Huynh, Y. Nakamori, Notes on "Reducing Algorithm Complexity for Computing an Aggregate Uncertainty Measure", IEEE Transactions on Cybernetics-Part A: Systems and Humans 40: 205-209, 2010.
 - ▶ M. Grabisch. Belief functions on lattices. International Journal of Intelligent Systems, 24:76-95, 2009.