

# Symbolic verification of distance bounding protocols

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EMSEC



# Introduction

## Security protocols

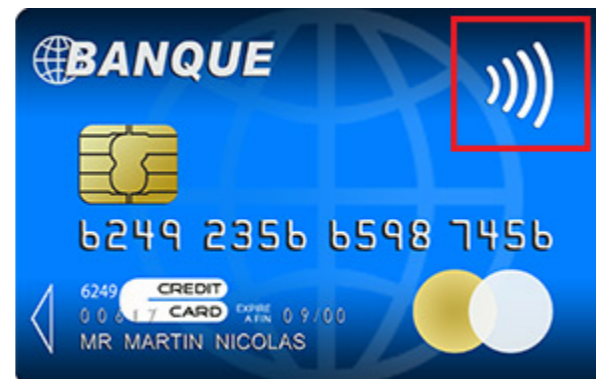
**Distributed programs** that use cryptographic primitives to ensure **security properties**.

Secrecy

Authentication

Integrity

Untraceability



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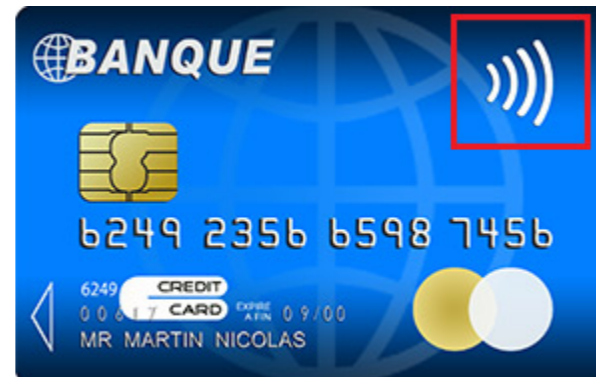
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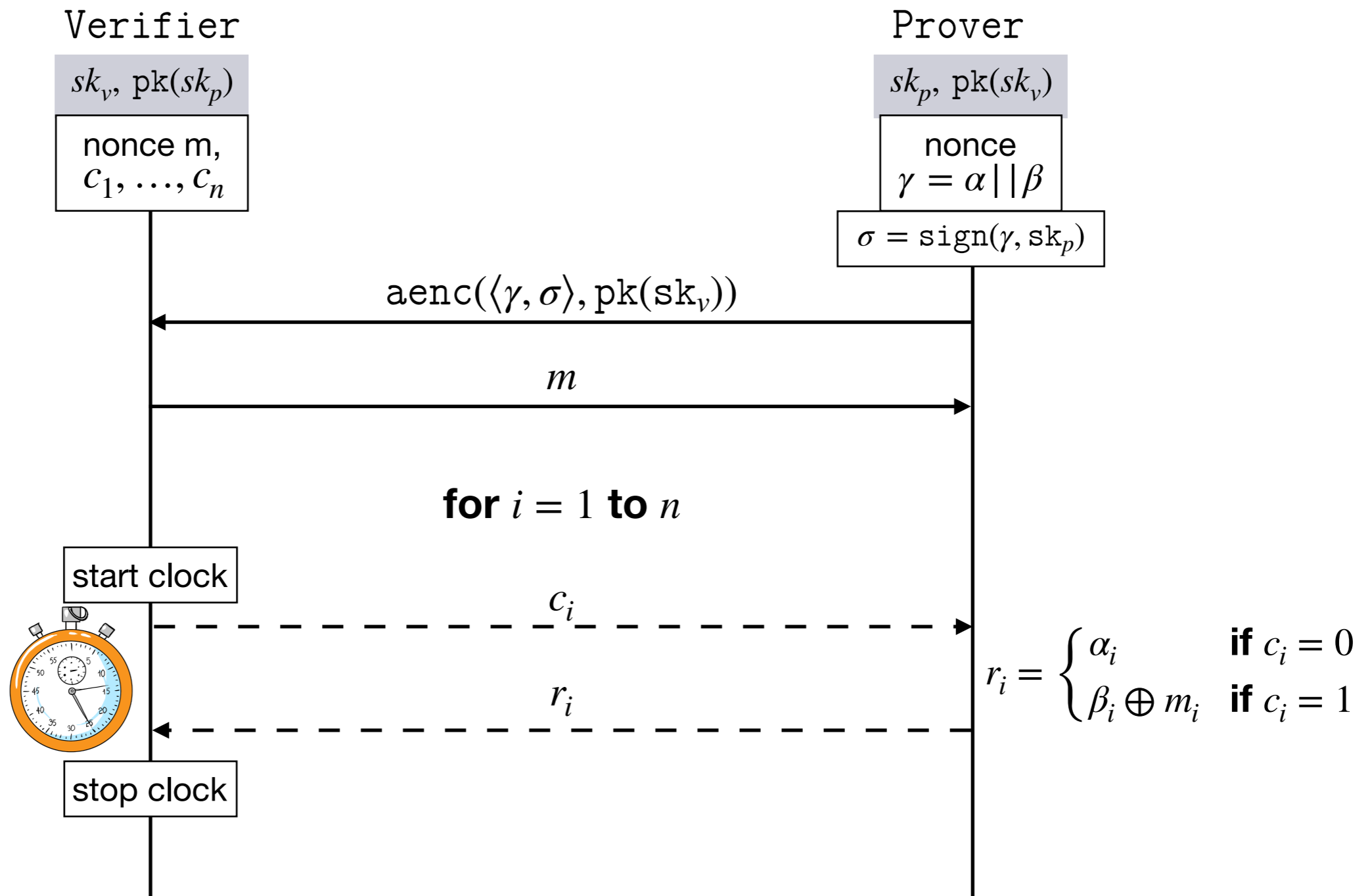
Integrity

Untraceability



**Authentication with physical proximity**

# Example: TREAD - 2017



# Symbolic verification

## Unbounded number of sessions

- ▶ **undecidable** in general
- ▶ tools may not terminate or lead to false attacks...
- ▶ tools: ProVerif, Tamarin...

[Durgin et al - 99]

## Bounded number of sessions

- ▶ **decidable** for many classes of protocols

[Rusinovitch et al - 01] [Millen et al - 01] [Comon et al - 03]

- ▶ tools implement exact procedures
- ▶ tools: OFMC, Akiss...

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- ▶ tools implement exact procedures
- ▶ tools: OFMC, Akiss...

**But not adapted to analyse DB protocols!**

# Symbolic verification of DB protocols

## Unbounded number of sessions

- ▶ existing tools **can be used** to verify DB protocols
- ▶ Tamarin: [Mauw et al - 18]
- ▶ ProVerif: [Chothia et al - 18] [Debant et al -18]

## Bounded number of sessions

### Contribution in this work

We extend the tool **Akiss** to be able to analyse DB protocols:

- ▶ adapt the model to take time into account
- ▶ provide an exact procedure

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Case studies



# Term algebra



**Messages:** terms but over a set of **names**  $\mathcal{N}$  and a **signature**  $\Sigma$  given with a **rewriting system**  $R$  satisfying the finite variant property.

## Example

- ▶ Names:  $\mathcal{N} = \{a, n, k\}$
- ▶ Signature:  $\Sigma = \{\text{aenc}, \text{adec}, \text{pk}, \text{pair}, \text{proj}_1, \text{proj}_2, \text{sign}, \text{getmsg}, \text{check}, \text{ok}, \}$
- ▶  $\text{adec}(\text{aenc}(x, \text{pk}(y)), y) = x$
- ▶  $\text{getmsg}(\text{sign}(x, y)) = x$
- ▶  $\text{proj}_1(\text{pair}(x, y)) = x$
- ▶  $\text{check}(\text{sign}(x, y), \text{pk}(y)) = \text{ok}$
- ▶  $\text{proj}_2(\text{pair}(x, y)) = y$

# Protocols

A trace  $T$  is a finite sequence of pairs, i.e.  $T = (a_1, a_1) \dots (a_n, a_n)$  where each  $a_i \in \mathcal{A}$  and  $a_i$  is an action of the form:

- ▶  $\text{out}^z(u)$                       output
- ▶  $\text{in}^z(x)$                         input
- ▶  $[v = v']$                         test equality
- ▶  $[z := v]$                         affectation of a timing variable
- ▶  $[|t_1 \sim t_2|]$                     timing constraint

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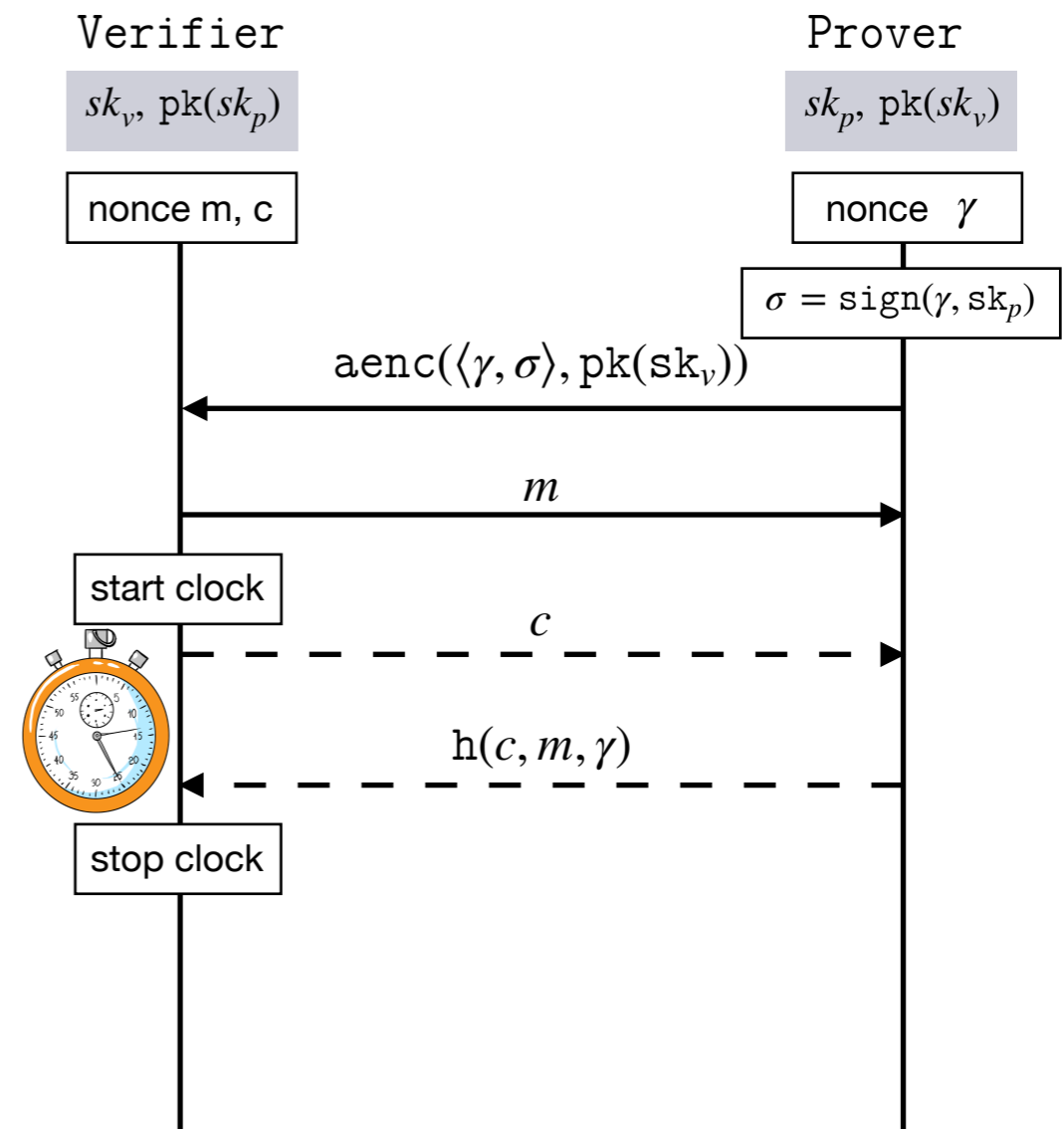
A protocol is a finite set of traces  $(T_1, \dots, T_k)$  describing all the possible interleavings of the considered sessions.

# Example: TREAD - 2017

$$T_V =$$

$(v, \text{in}(x)).$   
 $(v, [\text{check}(t_\sigma, \text{pk}(sk_p)) = \text{ok}]).$   
 $(v, [t_\gamma = \text{getmsg}(t_\sigma)]).$   
 $(v, \text{out}(m)).$   
 $(v, \text{out}^{z_1}(c)).$   
 $(v, \text{in}^{z_2}(y)).$   
 $(v, [|z_2 - z_1| < 2 \times t_0]).$   
 $(v, [y = h(c, m, t_\gamma)])$

with  $t_\sigma = \text{proj}_2(\text{adec}(x, sk_v))$   
 $t_\gamma = \text{proj}_1(\text{adec}(x, sk_v))$

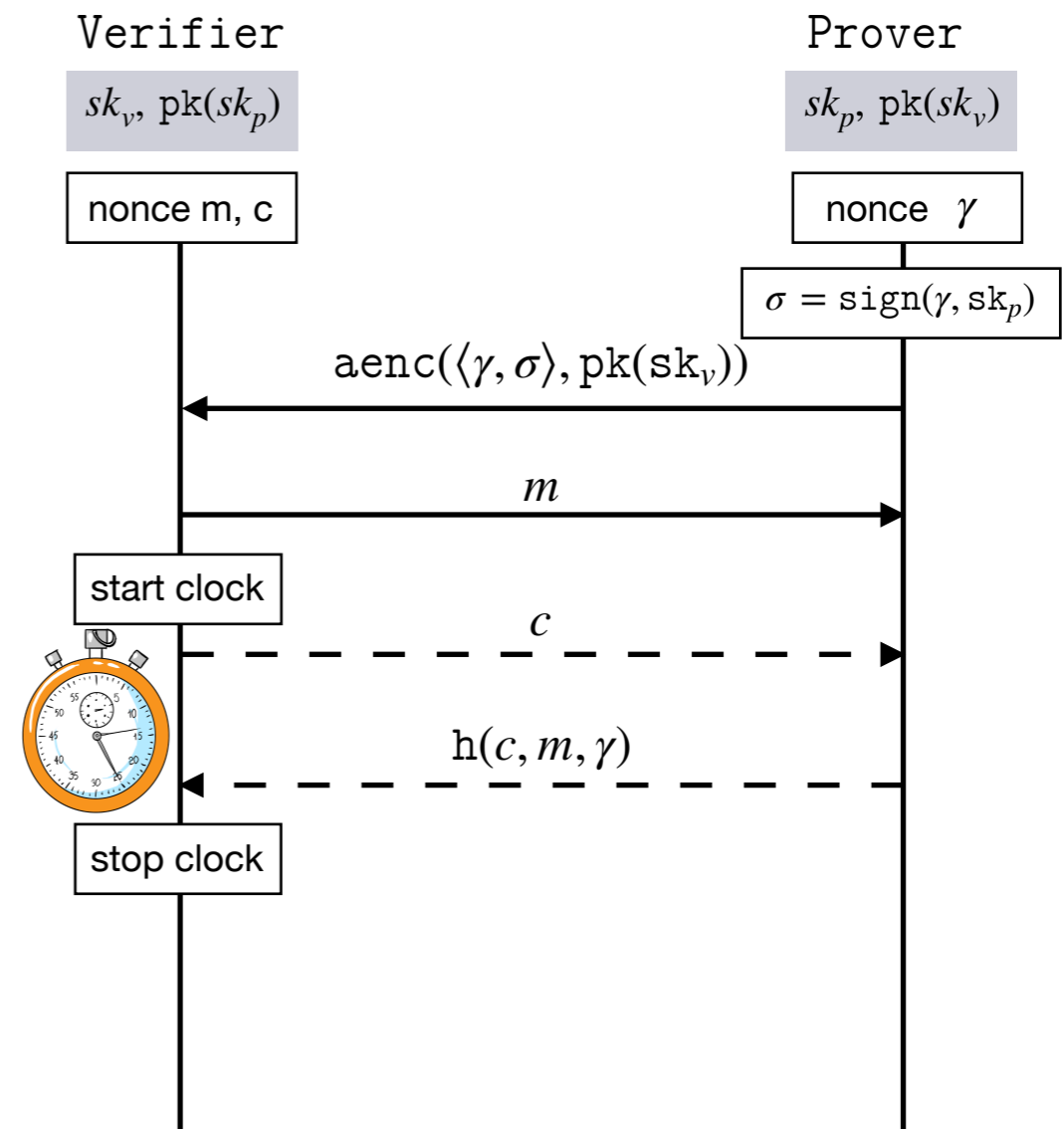


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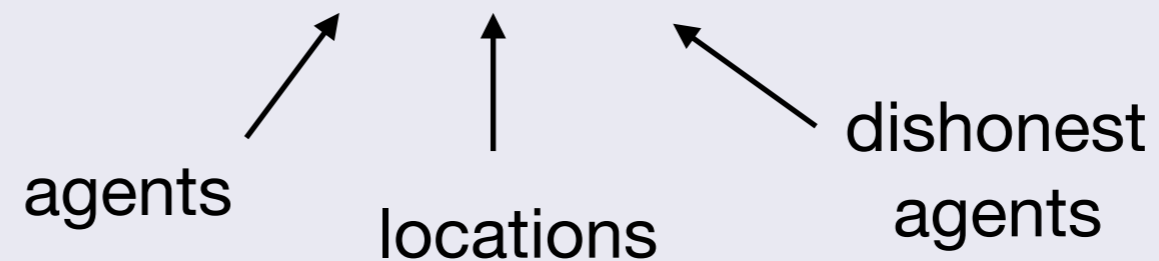


The protocol TREAD is the set of **all the possible interleaving** of  $T_V$  and  $T_P$  (the trace corresponding to the prover)

# Topology and Configuration

## Topology

A **topology** is a tuple  $\mathcal{T} = (\mathcal{A}, \text{Loc}, \mathcal{M})$ .

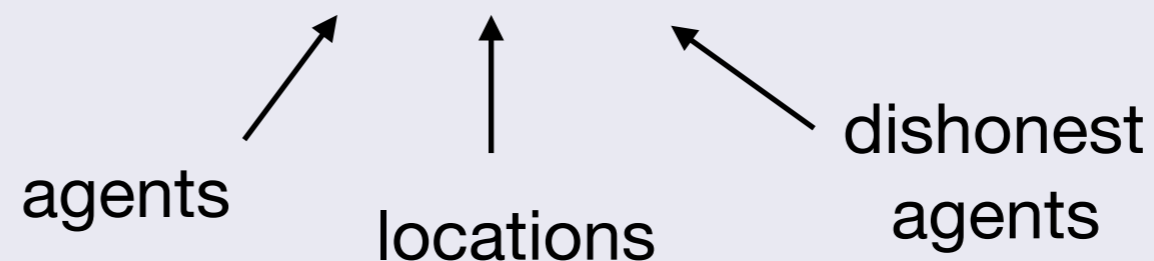


We define  $\text{Dist}_{\mathcal{T}}(a, b) = \frac{\|\text{Loc}(a) - \text{Loc}(b)\|}{c}$

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## Configuration

A **configuration** is a tuple  $(T; \Phi; t)$  where:

- ▶  $T$  is a trace
- ▶  $\Phi = \{w_1 \xrightarrow{a_1, t_1} m_1, \dots, w_n \xrightarrow{a_n, t_n} m_n\}$  is a frame
- ▶  $t \in \mathcal{R}_+$  is the global time

# Semantics

**TIME**  $(T; \Phi; t) \longrightarrow_{\mathcal{T}_0} (T; \Phi; t + \delta)$  with  $\delta \geq 0$

**TEST**  $((a, [|t_1 \sim t_2|]). T; \Phi; t) \xrightarrow{a, \text{test}}_{\mathcal{T}_0} (T; \Phi; t)$  when  $t_1 \sim t_2$  is true

**EQ**  $((a, [u = v]). T; \Phi; t) \xrightarrow{a, \text{eq}}_{\mathcal{T}_0} (T; \Phi; t)$  when  $u \downarrow = v \downarrow$

**LET**  $((a, [z := v]). T; \Phi; t) \xrightarrow{a, \text{let}(v \downarrow)}_{\mathcal{T}_0} (T\{z \mapsto v \downarrow\}; \Phi; t)$  when  $v \downarrow \in \mathbb{R}^+$

**OUT**  $((a, \text{out}^z(u)). T; \Phi; t) \xrightarrow{a, \text{out}(u \downarrow)}_{\mathcal{T}_0} (T\{z \mapsto t\}; \Phi \uplus \{w \xrightarrow{a, t} u \downarrow\}; t)$



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**IN**  $((a, \text{in}^z(x)). T; \Phi; t) \xrightarrow{a, \text{in}(u)}_{\mathcal{T}_0} (T\{x \mapsto u, z \mapsto t\}; \Phi; t)$

if  $\exists b \in \mathcal{A}, t_b \in \mathcal{R}_+$  such that  $t_b \leq t - \text{Dist}_{\mathcal{T}_0}(b, a)$  and:

- ▶ if  $b \notin \mathcal{M}$  then  $u \in \text{img}([\Phi]_b^{t_b}) \cup \mathcal{N}_{\text{pub}} \cup \mathbb{R}^+$
- ▶ if  $b \in \mathcal{M}$  then  $u$  is deducible from  $\bigcup_{c \in \mathcal{A}} [\Phi]_c^{t_b - \text{Dist}_{\mathcal{T}_0}(c, b)}$

# Problem under study

## Reachability property

A reachability property is a property that can be encoded in the following decision problem:

**Input:** A trace  $T$  and topology  $\mathcal{T}_0$

**Output:** Do there exist  $l_1, \dots, l_n, \Phi$  and  $t$  such that

$$(T, \emptyset, t_0) \xrightarrow{l_1, \dots, l_n} \mathcal{T}_0 (\epsilon; \Phi; t)?$$

### Distance bounding protocols:

Resistance against **Distance frauds**, **Mafia frauds**, **Distance hijacking attacks** is equivalent to: given a topology,

"can a verifier end a session talking with a remote prover?"

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## Main issue

$$T = (a_1, \text{out}(k)) . (a_2, \text{out}(k)) . (b, \text{in}^z(x)) . (b, [x = k]) . (b, [|z < 2|])$$

With  $\text{Dist}_{\mathcal{T}}(a_1, b) = 10$

$$\text{Dist}_{\mathcal{T}}(a_2, b) = 1$$

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**Is the configuration  $(T; \emptyset, 0)$  executable?**

Yes **but only** considering  $w_2$  as an input recipe.

### **Issue:**

**The Akiss procedure will arbitrary drop one of the two outputs deducing the same term...**

# Akiss procedure

**Input:** two traces  $T$  and  $P$

**Output:** check if  $T \sqsubseteq P$



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$$r_{(a_1, \text{out}(k)).(a_2, \text{out}(k)).(b, \text{in}(k)).(b, \text{eq}).(b, \text{test})} \Leftarrow k_{(a_1, \text{out}(k)).(a_2, \text{out}(k))}(X, k)$$

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- ▶ finite set of **simple** Horn clauses

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**Step 3:** check the trace inclusion

- ▶ for all the reachability statement in the saturated knowledge base, Check that it can be executed in P

# Our procedure

**Input:** a trace and a topology

**Output:** is\_secure/attack

**Step 2:** compute the saturated knowledge base

- ▶ finite set of **simple** Horn clauses
- ▶ dropping less clauses than Akiss does, to keep completeness

**Step 3:** check the timing constraints

- ▶ for all the witnesses of attack (i.e. a reach predicate) in the saturated knowledge base:
  - compute all the recipes that can fill the inputs
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# Horn clause

$$H \Leftarrow k_{w_1}(X_1, u_1), \dots, k_{w_n}(X_n, u_n) \quad \text{with } H \in \{r_{w_0}, k_{w_0}(R, u)\}$$

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- reach:  $(T_0; \Phi_0) \models r_{l_1, \dots, l_n}$  if there exists  $(T_n; \Phi_n)$  such that  $(T_0; \Phi_0) \xrightarrow{l_1, \dots, l_n} (T_n; \Phi_n)$

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$$H \Leftarrow \mathbf{k}_{w_1}(X_1, u_1), \dots, \mathbf{k}_{w_n}(X_n, u_n) \quad \text{with } H \in \{\mathbf{r}_{w_0}, \mathbf{k}_{w_0}(R, u)\}$$

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► knows:  $(T_0; \Phi_0) \models \mathbf{k}_{l_1, \dots, l_n}(R, u)$  if for all  $(T_n; \Phi_n)$  such that  $(T_0; \Phi_0) \xrightarrow{l_1, \dots, l_n} (T_n; \Phi_n)$

we have that  $R\Phi_n \downarrow = u$



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we have that  $R\Phi_n \downarrow = u$

**This semantics is given w.r.t. an untimed semantics of traces!**

# Saturation

**Step 2:** compute the saturated knowledge base

- ▶ finite set of **simple** Horn clauses
- ▶ **dropping less clauses than Akiss does, to keep completeness**

$$f : H \Leftarrow \text{k}_w(X, t), B_1, \dots, B_n \in K \quad t \notin \mathcal{X}$$

$$g : \text{k}_{w'}(R', t') \Leftarrow B_{n+1}, \dots, B_m \in \text{solved}(K) \quad \sigma = \text{mgu}(\text{k}_w(X, t), \text{k}_{w'}(R', t'))$$

Resolution

---


$$K := K \cup (H \Leftarrow B_1, \dots, B_n, B_{n+1}, \dots, B_m)\sigma$$

## New update function

1. Do not add the statement if the term in the head is reduced to a variable
2. Simplify the statement i.e. if  $B_i = \text{k}_w(X_i, u)$  and  $B_j = \text{k}_w(X_j, u)$  keep only one

# Saturation

## Soundness of the saturation

Given a trace  $T$ , we denote  $K = \text{solved}(\text{sat}(\text{seed}(T)))$  and

$$(T, \emptyset) \models g \text{ for any } g \in K \cup \mathcal{H}(K)$$

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## Completeness of the saturation

Given a trace  $T$ , we denote  $K = \text{solved}(\text{sat}(\text{seed}(T)))$  and

if  $(T, \emptyset) \xrightarrow{l_1, \dots, l_n}_{\mathcal{T}} (S, \phi)$  with **asap** input recipes then

- $r_{l_1, \dots, l_n} \in \mathcal{H}(K)$
- if  $R\phi \downarrow = u$  for some  $R$  **asap** then  $k_{l_1, \dots, l_p}(R, u) \in \mathcal{H}(K)$

## Lemma

Given an execution  $(T, \emptyset) \xrightarrow{l_1, \dots, l_n}_{\mathcal{T}} (S, \phi)$  w.l.o.g. we can assume that it only involves asap input recipes.

# Algorithm

```

1 :   procedure Reachability( $T, t_0, \mathcal{T}_0$ )
2 :      $K := \text{solved}(\text{sat}(\text{seed}(T)))$ 
3 :     for all  $r_{l_1, \dots, l_n} \Leftarrow k_{w_1}(X_1, x_1), \dots, k_{w_m}(X_m, x_m) \in K$  do
4 :       let  $c_1, \dots, c_q$  be fresh public names such that
5 :        $\rho : \text{vars}(l_1, \dots, l_n) \rightarrow \{c_1, \dots, c_k\}$  is a bijection
6 :       for all  $i \in \text{Rcv}(n)$  do
7 :         if  $l_i = (a_i, \text{in}(v_i))$  then  $\bar{L}_i = \{R \mid k_{l_1\rho, \dots, l_n\rho}(R, v_i\rho) \in \mathcal{H}(K)\}$ 
8 :       end for
9 :       let  $\{i_1, \dots, i_p\} = \text{Rcv}(n)$ 
10 :      for all  $R_{i_1}, \dots, R_{i_p} \in \bar{L}_{i_1}, \dots, \bar{L}_{i_p}$  do
11 :        let  $\psi = \text{Timing}((T, \emptyset, t_0), R_{i_1} \dots R_{i_p}, l_1, \dots, l_n)$ 
12 :        if  $\psi$  satisfiable then return true end if
13 :      end for
14 :    end for
15 :    return false
16 :  end procedure

```

# Procedure

## Soundness and completeness of the procedure

Given a trace  $T$ :

- ▶ If our procedure returns "attack" then there exists  $l_1, \dots, l_n, \Phi_n, t_n$  such that:  $(T, \emptyset) \xrightarrow{l_1, \dots, l_n} (\epsilon, \Phi_n)$
- ▶ If our procedure returns "is\_secure" then the empty trace  $\epsilon$  is not reachable.

**Limitation:** we did not prove the termination of our procedure.

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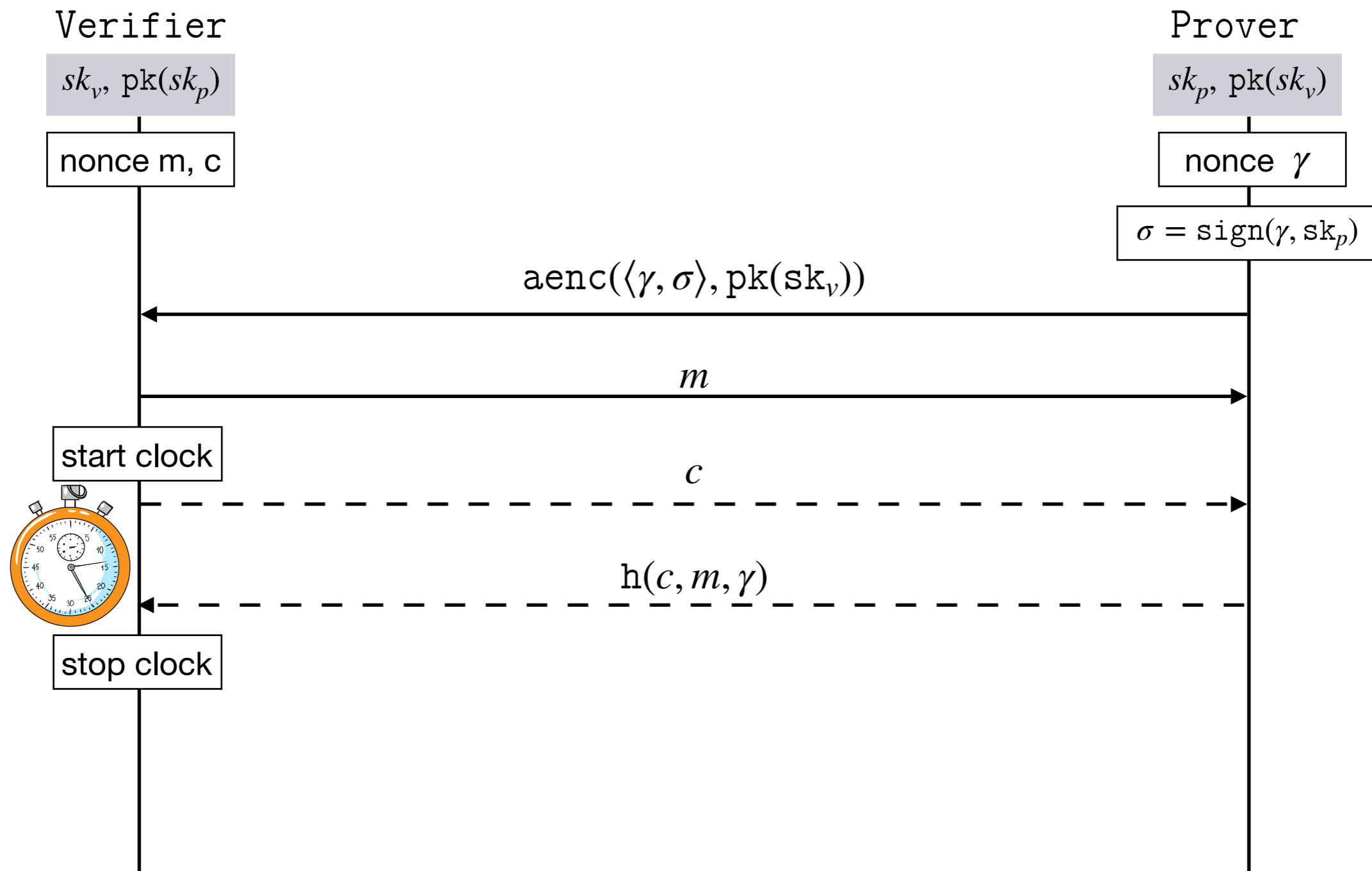
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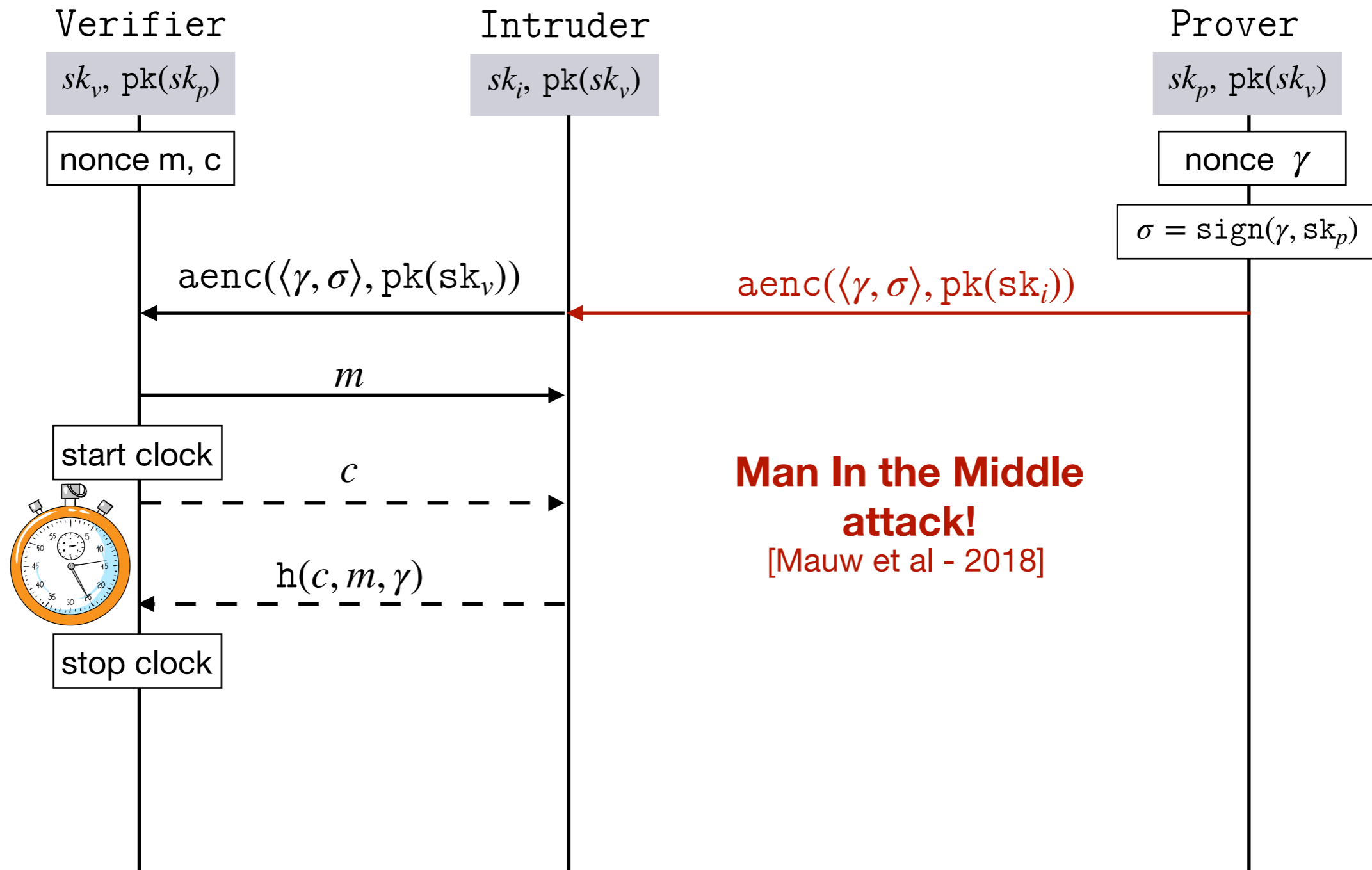
**Case studies**

# TREAD - 2017

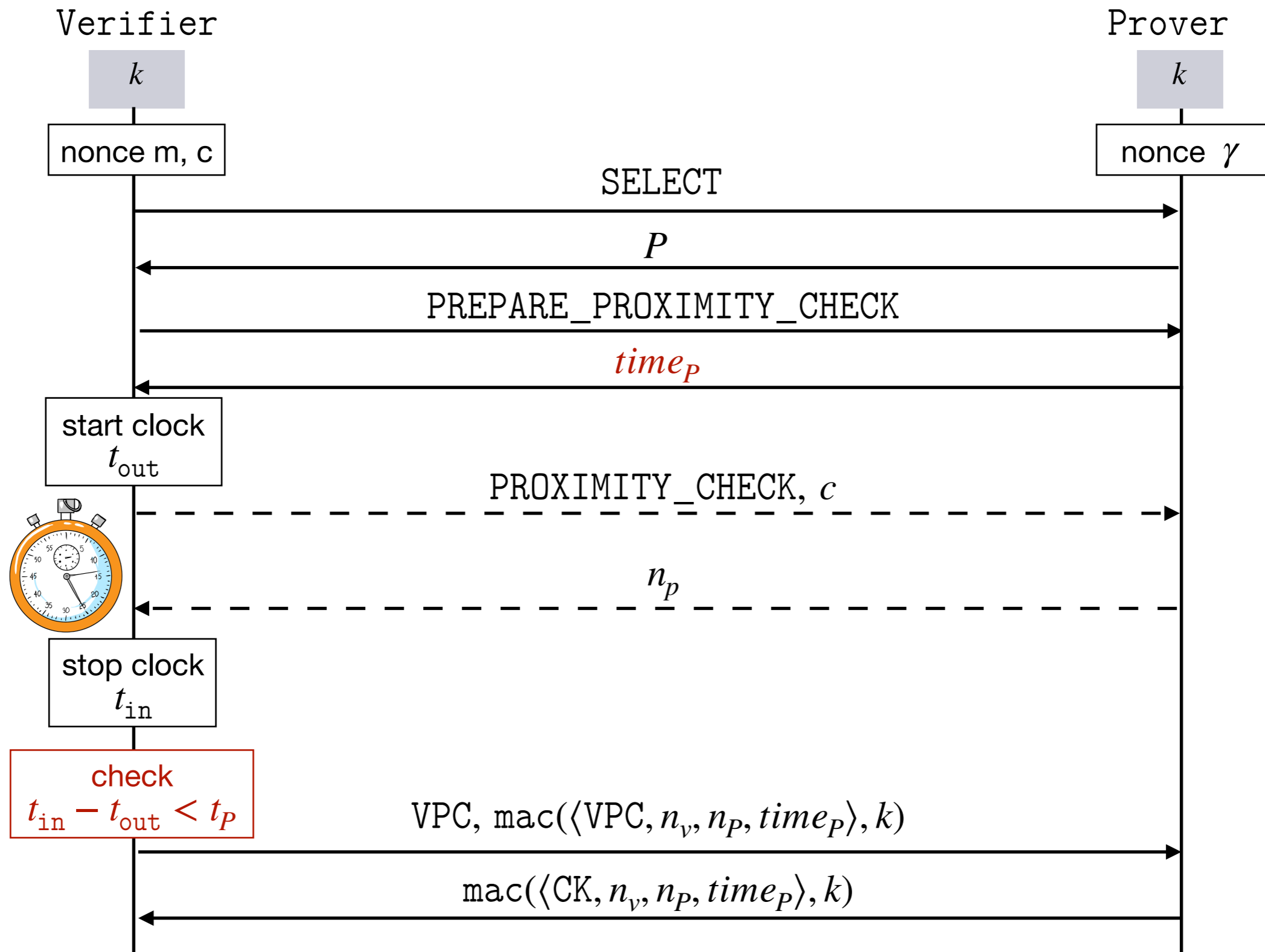




# TREAD - 2017



# NXP protocol - 2017



## Case studies

Protocols	MF			DH		
	roles/tr	time	status			
TREAD-Asymmetric	2/-	1s	✗	2/-	1s	✗
SPADE	2/-	2s	✗	2/-	4s	✗
TREAD-Symmetric	4/7500	18min	✓	2/-	1s	✗
Brands and Chaum	4/5635	37min	✓	2/-	1s	✗
Swiss-Knife	3/1080	25s	✓	3/7470	4min	✓
Hancke and Kuhn	2/20	1s	✓	2/20	1s	✓
	4/3368	58s	✓	4/3368	47s	✓
	5/30240	14min	✓	5/30240	12min	✓
NXP	2/126	4s	✓			
Mastercard RRP	2/35	6min	✓			
PaySafe	2/4	5min	✓			

( ✗ : attack found, ✓ : proved secure)

# Conclusion

As expected we have adapted the underlying procedure of Akiss to propose an **exact procedure** to analyze distance bounding protocols. We have **successfully applied** it to many protocols.

## Future work

- ▶ Improve the POR optimization to limit the interleaving blow up
- ▶ Improve the update function to avoid non-termination issues
- ▶ Adapt this procedure to model XOR